

MAX5214/MAX5216

14-/16-Bit, Low-Power, Buffered Output, Rail-to-Rail DACs with SPI Interface

General Description

The MAX5214/MAX5216 are pin-compatible, 14-bit and 16-bit digital-to-analog converters (DACs). The MAX5214/MAX5216 are single-channel, low-power, buffered voltage-output DACs. The devices use a precision external reference applied through the high resistance input for rail-to-rail operation and low system power consumption. The MAX5214/MAX5216 accept a wide 2.7V to 5.5V supply voltage range. Power consumption is extremely low to accommodate most low-power and low-voltage applications. These devices feature a 3-wire SPI-/QSPI™-/MICROWIRE®-/DSP-compatible serial interface to save board space and to reduce the complexity in isolated applications. The MAX5214/MAX5216 minimize the digital noise feedthrough from input to output with SCLK and DIN input buffers powered down after completion of each serial input frame. On power-up, the MAX5214/MAX5216 reset the DAC output to zero, providing additional safety for applications that drive valves or other transducers that need to be off on power-up. The DAC output is buffered resulting in a low supply current of 80μA (max) and a low offset error of ±0.25mV. A zero level applied to the $\overline{\text{CLR}}$ pin asynchronously clears the contents of the input and DAC registers and sets the DAC output to zero independent of the serial interface. The MAX5214/MAX5216 are available in an ultra-small (3mm x 5mm), 8-pin μMAX® package and are specified over the -40°C to +105°C extended industrial temperature range.

Applications

2-Wire Sensors
 Communication Systems
 Automatic Tuning
 Gain and Offset Adjustment
 Power Amplifier Control
 Process Control and Servo Loops
 Portable Instrumentation
 Programmable Voltage and Current Sources
 Automatic Test Equipment

QSPI is a trademark of Motorola, Inc.

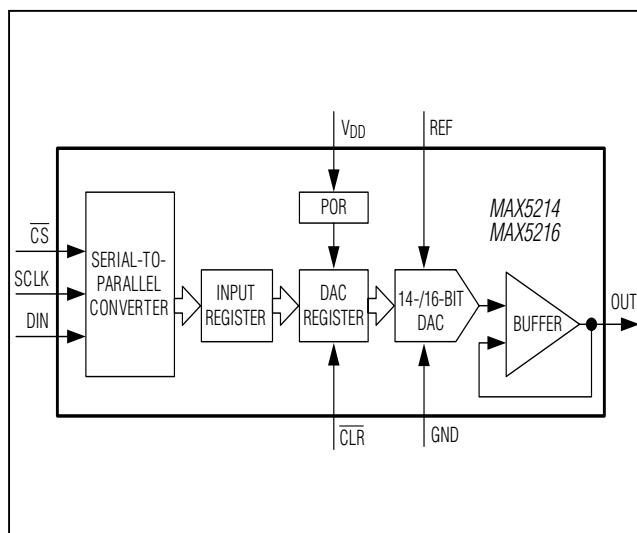
MICROWIRE is a registered trademark of National Semiconductor Corp.

μMAX is a registered trademark of Maxim Integrated Products, Inc.

Features

- ◆ Low-Power Consumption (80μA max)
- ◆ 14-/16-Bit Resolution in a 3mm x 5mm, 8-Pin μMAX Package
- ◆ Relative Accuracy
 - ±0.40 LSB INL (MAX5214, 14-Bit typ, ±1 LSB max)
 - ±1.2 LSB INL (MAX5216, 16-Bit typ, ±4 LSB max)
- ◆ Guaranteed Monotonic Over All Operating Ranges
- ◆ Low Gain and Offset Error
- ◆ Wide 2.7V to 5.5V Supply Range
- ◆ Rail-to-Rail Buffered Output Operation
- ◆ Safe Power-On Reset (POR) to Zero DAC Output
- ◆ Fast 50MHz, 3-Wire, SPI/QSPI/MICROWIRE-Compatible Serial Interface
- ◆ Schmitt-Trigger Inputs for Direct Optocoupler Interface
- ◆ Asynchronous $\overline{\text{CLR}}$ Clears DAC Output to Code 0
- ◆ High Reference Input Resistance for Power Reduction
- ◆ Buffered Voltage Output Directly Drives 10kΩ Loads

Functional Diagram



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ABSOLUTE MAXIMUM RATINGS

VDD to GND -0.3V to +6V
 REF, OUT, $\overline{\text{CLR}}$ to GND -0.3V to the lower of
 (VDD + 0.3V) and +6V
 SCLK, DIN, $\overline{\text{CS}}$ to GND -0.3V to +6V
 Continuous Power Dissipation (TA = +70°C)
 μMAX (derate at 4.8mW/°C above +70°C) 387mW

Maximum Current into Any Input or Output $\pm 50\text{mA}$
 Operating Temperature Range -40°C to +105°C
 Storage Temperature Range -65°C to +150°C
 Lead Temperature (soldering, 10s) +300°C
 Soldering Temperature (reflow) +260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

PACKAGE THERMAL CHARACTERISTICS (Note 1)

μMAX Junction-to-Case Thermal Resistance (θ_{JC}) 42°C/W
 Junction-to-Ambient Thermal Resistance (θ_{JA}) 206°C/W

Note 1: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to www.maximintegrated.com/thermal-tutorial.

ELECTRICAL CHARACTERISTICS

(VDD = 2.7V to 5.5V, VREF = 2.5V to VDD, CL = 60pF, RL = 10k Ω , TA = -40°C to +105°C, unless otherwise noted. Typical values are at TA = +25°C.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
STATIC ACCURACY (Note 3)						
Resolution	N	MAX5214	14			Bits
		MAX5216	16			
Integral Nonlinearity	INL	MAX5214 (14-bit) (Note 4)	-1	± 0.4	+1	LSB
		MAX5216 (16-bit) (Note 4)	-4	± 1.2	+4	
		MAX5216B (16-bit) (Note 4)	-8	± 3	+8	
Differential Nonlinearity	DNL	MAX5214 (14-bit) (Note 4)	-1	± 0.1	+1	LSB
		MAX5216 (16-bit) (Note 4)	-1	± 0.25	+1	
Offset Error	OE	(Note 5)	-1.25	± 0.25	+1.25	mV
Offset-Error Drift				± 1.6		$\mu\text{V}/^\circ\text{C}$
Gain Error	GE	(Note 5)	-0.06	-0.04	0	%FS
Gain Temperature Coefficient				± 2		ppmFS/ °C
REFERENCE INPUT						
Reference-Input Voltage Range	VREF		2		VDD	V
Reference-Input Impedance	RREF		200	256		k Ω
DAC OUTPUT						
Output Voltage Range (Note 6)		No load (typical)			VDD	V
		10k Ω load to GND	0		VDD - 0.2	
		10k Ω load to VDD	0.2		VDD - 0.2	
DC Output Impedance				0.1		Ω
Capacitive Load (No Sustained Oscillations)	CL	Series resistance = 0 Ω		0.1		nF
		Series resistance = 1k Ω		15		μF

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ELECTRICAL CHARACTERISTICS (continued)

(V_{DD} = 2.7V to 5.5V, V_{REF} = 2.5V to V_{DD}, C_L = 60pF, R_L = 10k Ω , T_A = -40°C to +105°C, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Resistive Load (Note 6)	RL		5			k Ω
Short-Circuit Current		V _{DD} = 5.5V	-25	± 6	+25	mA
Power-Up Time		From power-down mode		25		μ s
DIGITAL INPUTS (SCLK, DIN, $\overline{\text{CS}}$, $\overline{\text{CLR}}$)						
Input High Voltage	V _{IH}		0.7 x V _{DD}			V
Input Low Voltage	V _{IL}				0.3 x V _{DD}	V
Input Leakage Current	I _{IN}	V _{IN} = 0V or V _{DD}		± 0.1	± 1	μ A
Input Capacitance	C _{IN}				10	pF
Hysteresis Voltage	V _{HYS}			0.15		V
DYNAMIC PERFORMANCE (Note 7)						
Voltage-Output Slew Rate	SR	Positive and negative		0.5		V/ μ s
Voltage-Output Settling Time		1/4 scale to 3/4 scale, to ≤ 0.5 LSB, 14-bit		18		μ s
Reference -3dB Bandwidth	BW	Hex code = 2000 (MAX5214), Hex code = 8000 (MAX5216)		100		kHz
Digital Feedthrough		Code = 0, all digital inputs from 0V to V _{DD} , SCLK < 50MHz		0.5		nV·s
DAC Glitch Impulse		Major code transition		2		nV·s
Output Noise		1kHz		73		nV/ $\sqrt{\text{Hz}}$
		10kHz		70		
Integrated Output Noise		0.1Hz to 10Hz		3.5		μ VP-P
POWER REQUIREMENTS						
Supply Voltage	V _{DD}		2.7		5.5	V
Supply Current	I _{DD}	No load; all digital inputs at 0V or V _{DD} , supply current only; excludes reference input current, midscale		70	80	μ A
Power-Down Supply Current	PDIDD	No load, all digital inputs at 0V or V _{DD}		0.4	2	μ A
TIMING CHARACTERISTICS (Notes 7 and 8) (Figures 1 and 2)						
Serial Clock Frequency	fSCLK		0		50	MHz
SCLK Pulse-Width High	t _{CH}		8			ns
SCLK Pulse-Width Low	t _{CL}		8			ns
$\overline{\text{CS}}$ Fall to SCLK Fall Setup Time	t _{CSS0}		8			ns
$\overline{\text{CS}}$ Fall to SCLK Fall Hold Time	t _{CSH0}		0			ns
$\overline{\text{CS}}$ Rise to SCLK Fall Hold Time	t _{CSH1}		0			ns
$\overline{\text{CS}}$ Rise to SCLK Fall	t _{CSA}				12	ns
SCLK Fall to $\overline{\text{CS}}$ Fall	t _{CSF}		100			ns
DIN to SCLK Fall Setup Time	t _{DS}		5			ns
DIN to SCLK Fall Hold Time	t _{DH}		4.5			ns
$\overline{\text{CS}}$ Pulse-Width High	t _{CSPW}		20			ns

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ELECTRICAL CHARACTERISTICS (continued)

($V_{DD} = 2.7V$ to $5.5V$, $V_{REF} = 2.5V$ to V_{DD} , $C_L = 60pF$, $R_L = 10k\Omega$, $T_A = -40^\circ C$ to $+105^\circ C$, unless otherwise noted. Typical values are at $T_A = +25^\circ C$.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
$\overline{CLR}$ Pulse-Width Low	t_{CLPW}		20			ns
$\overline{CLR}$ Rise to $\overline{CS}$ Fall	t_{CSC}		20			ns

Note 2: Electrical specifications are production tested at $T_A = +25^\circ C$ and $T_A = +105^\circ C$. Specifications over the entire operating temperature range are guaranteed by design and characterization. Typical specifications are at $T_A = +25^\circ C$ and are not guaranteed.

Note 3: Static accuracy tested without load.

Note 4: Linearity is tested within 20mV of GND and V_{DD} .

Note 5: Gain and offset is tested within 100mV of GND and V_{DD} .

Note 6: Subject to offset and gain error limits and V_{REF} settings.

Note 7: Guaranteed by design; not production tested.

Note 8: All timing specifications measured with $V_{IL} = V_{GND}$, $V_{IH} = V_{DD}$.

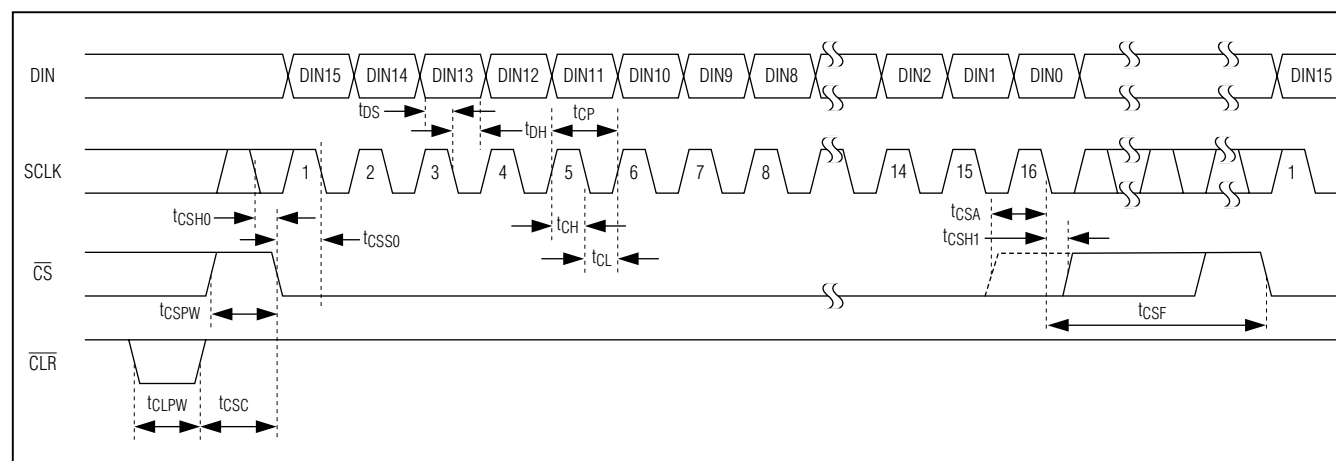


Figure 1. 16-Bit Serial-Interface Timing Diagram (MAX5214)

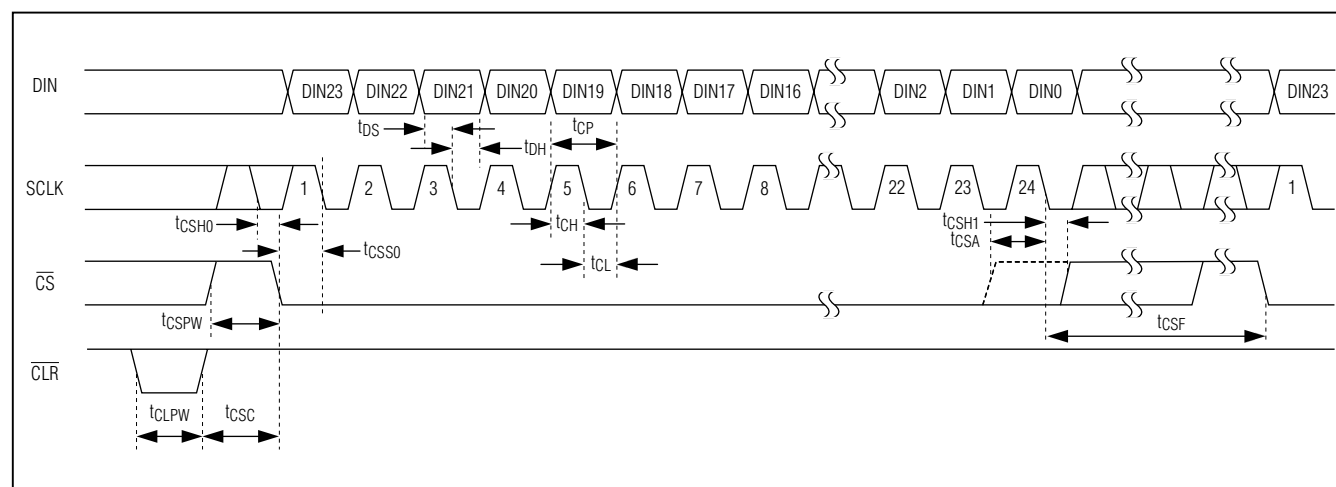


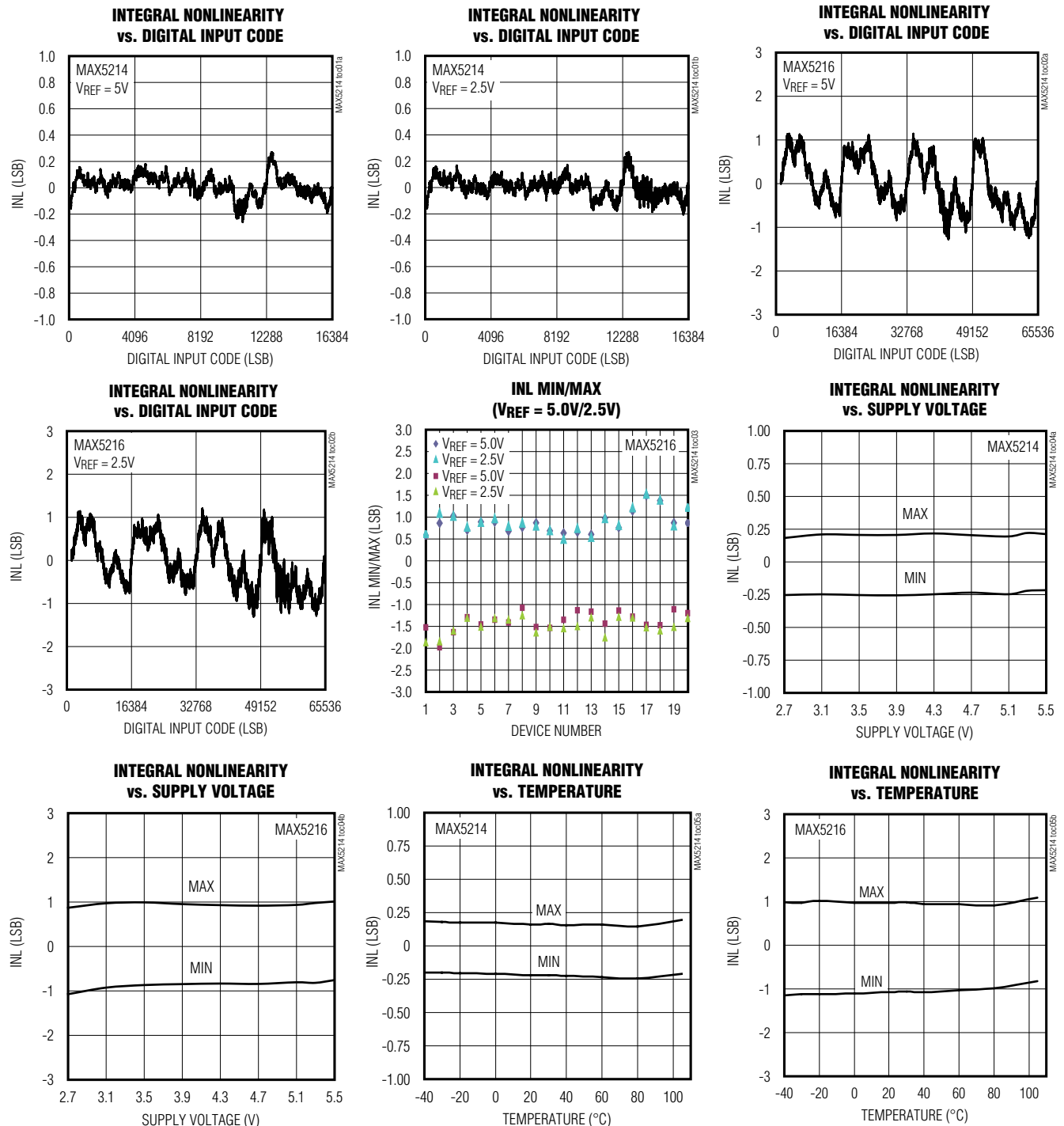
Figure 2. 24-Bit Serial-Interface Timing Diagram (MAX5216)

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Typical Operating Characteristics

(T_A = +25°C, unless otherwise noted.)

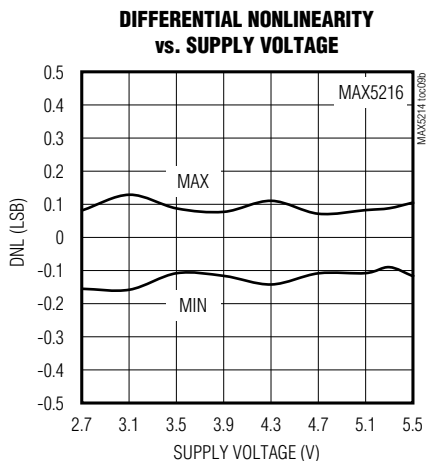
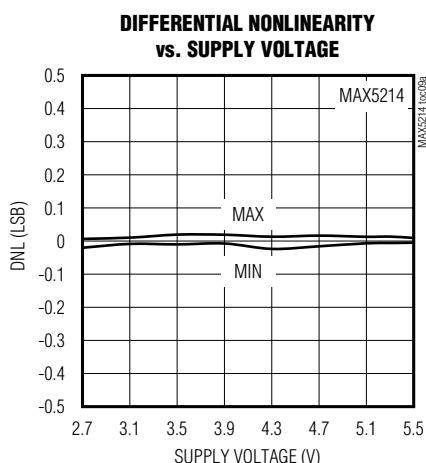
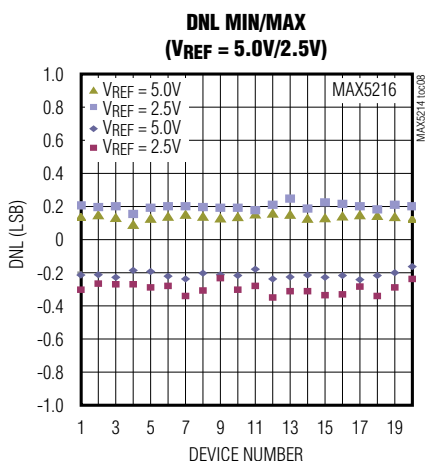
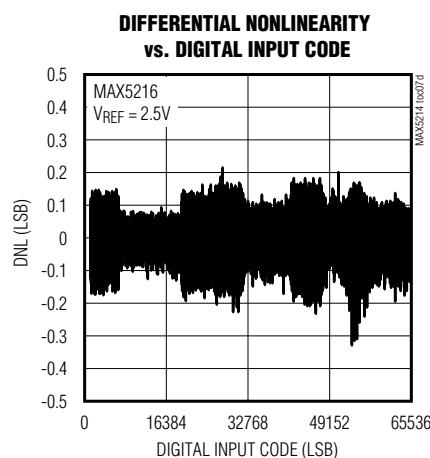
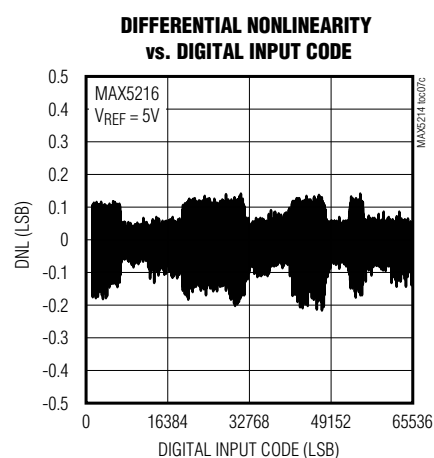
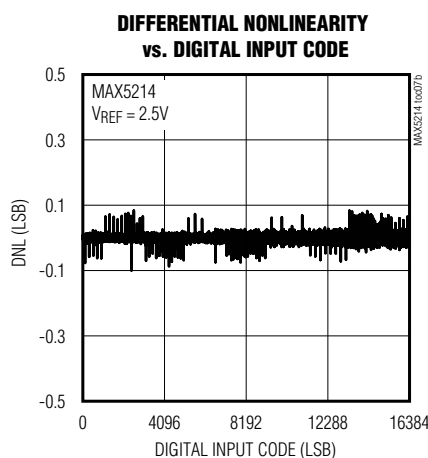
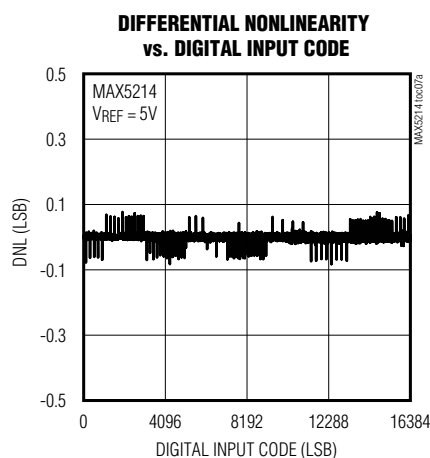
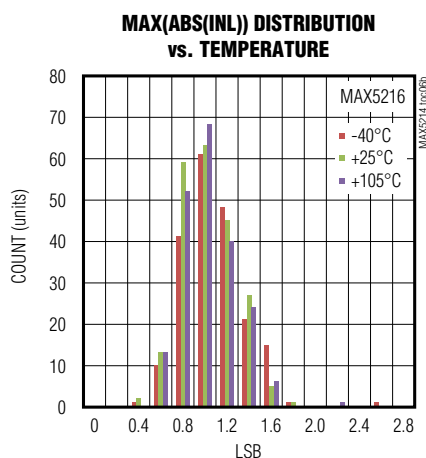
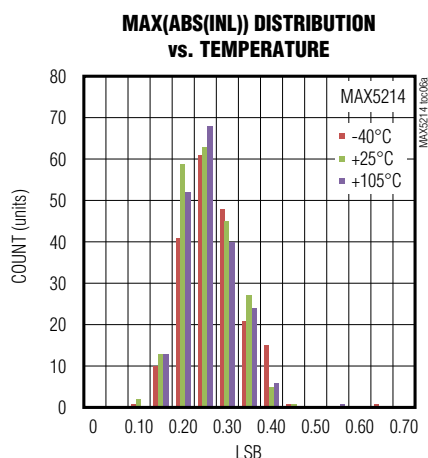


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Typical Operating Characteristics (continued)

($T_A = +25^\circ\text{C}$, unless otherwise noted.)

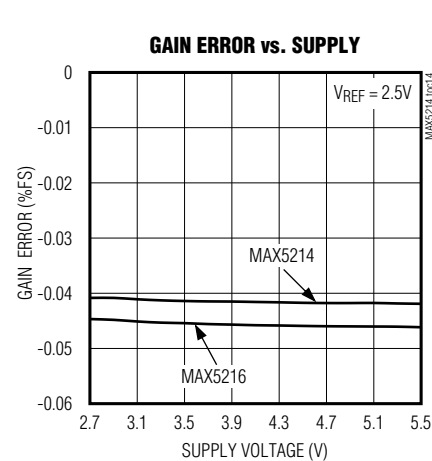
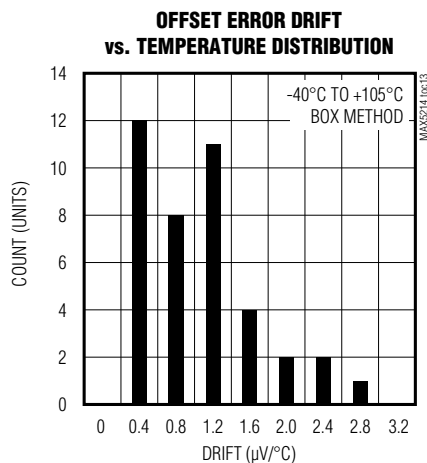
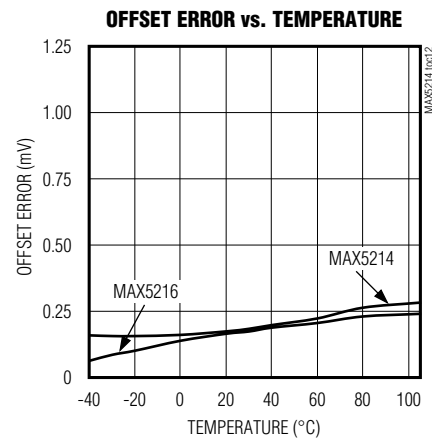
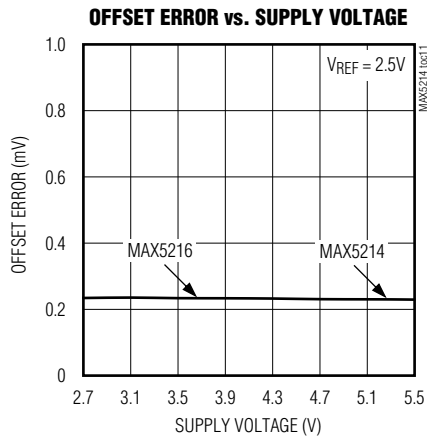
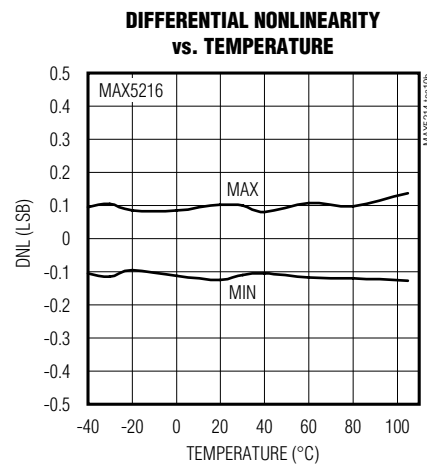
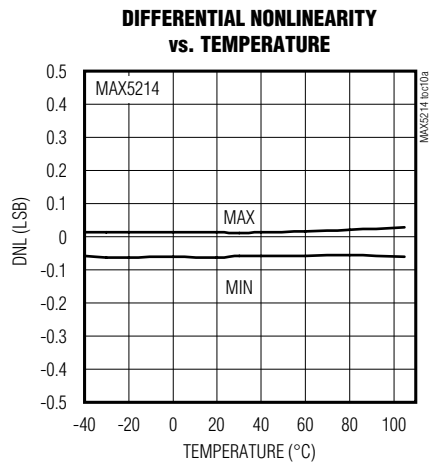


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Typical Operating Characteristics (continued)

(T_A = +25°C, unless otherwise noted.)

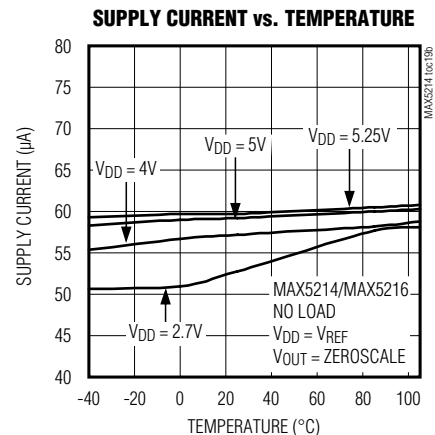
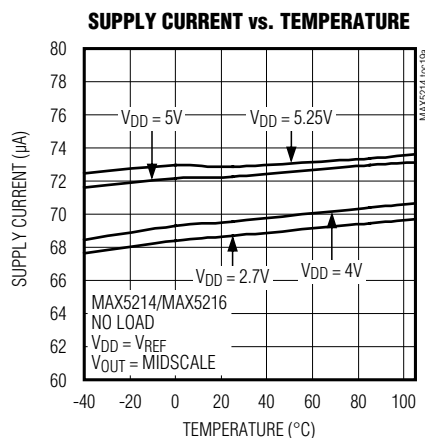
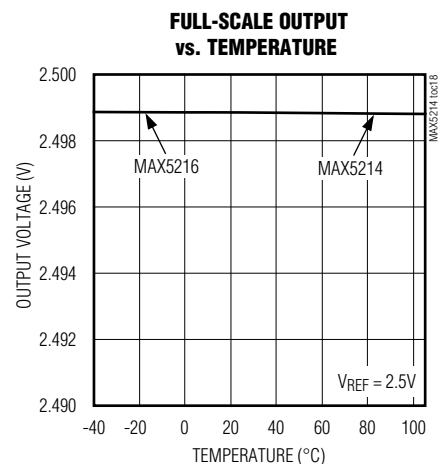
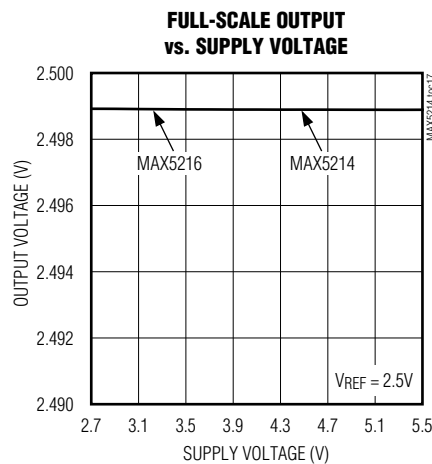
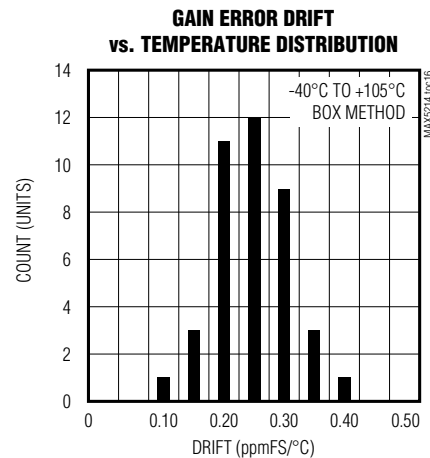
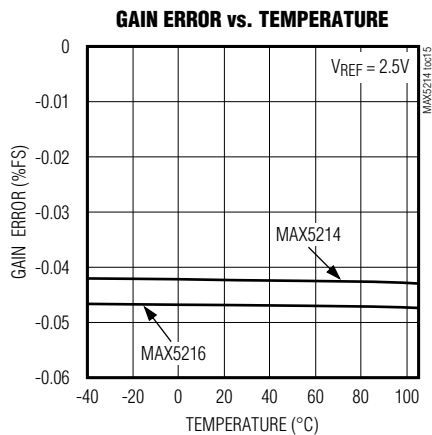


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Typical Operating Characteristics (continued)

($T_A = +25^\circ\text{C}$, unless otherwise noted.)

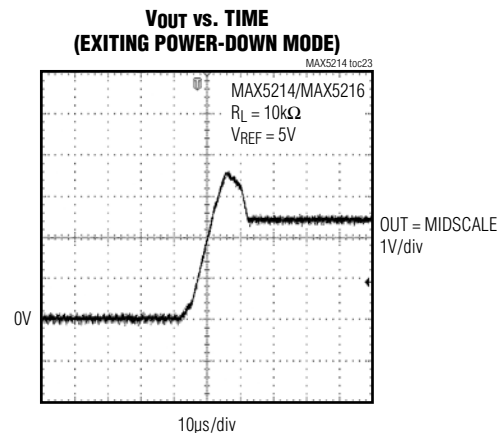
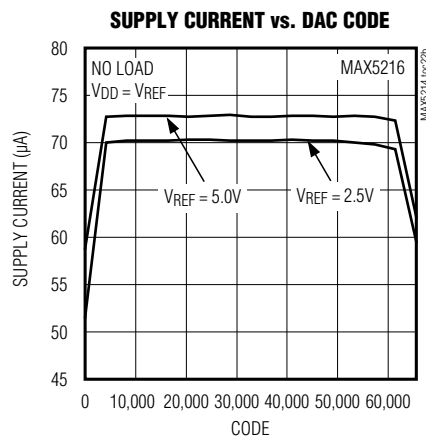
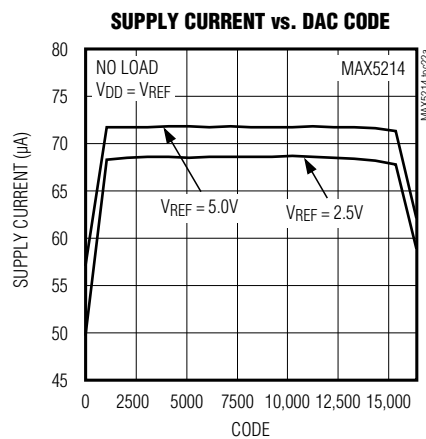
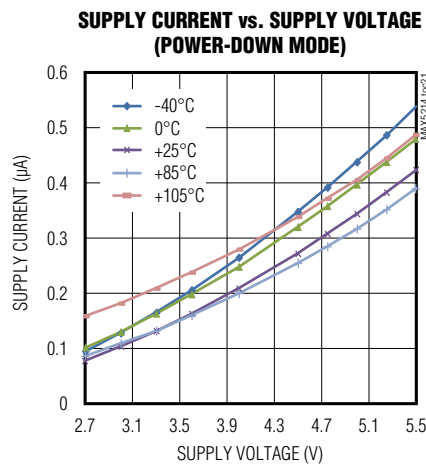
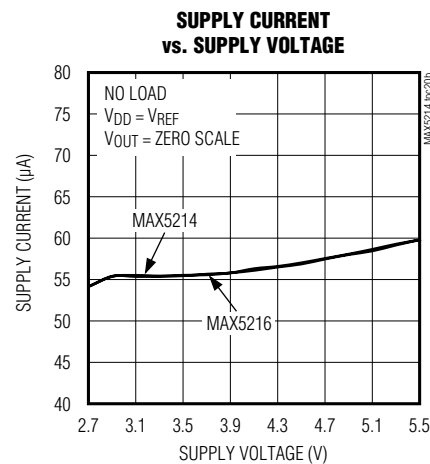
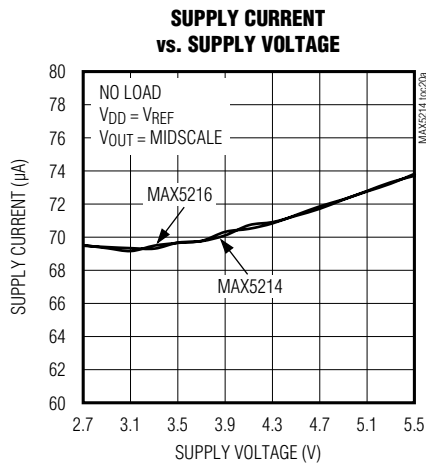


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Typical Operating Characteristics (continued)

($T_A = +25^\circ\text{C}$, unless otherwise noted.)



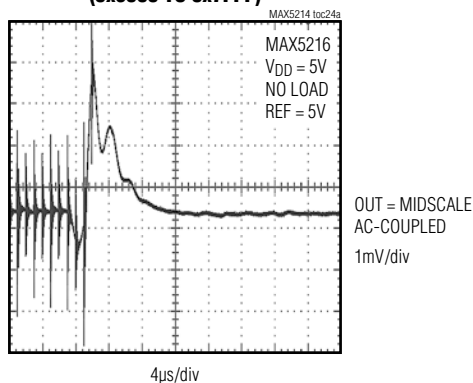
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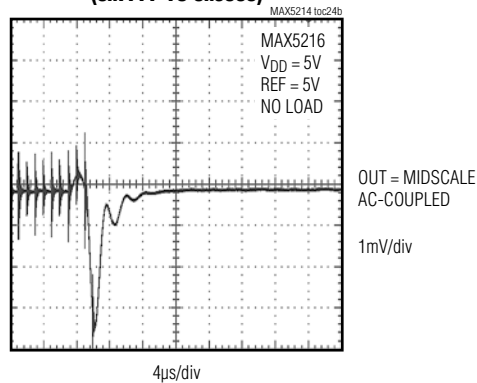
Typical Operating Characteristics (continued)

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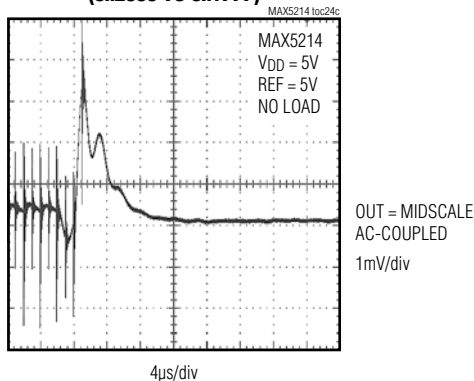
**MAJOR CODE TRANSITION
(0x8000 TO 0x7FFF)**



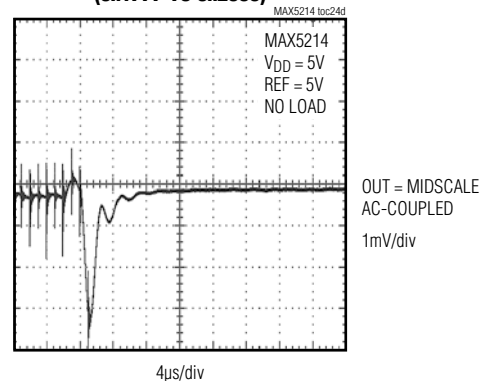
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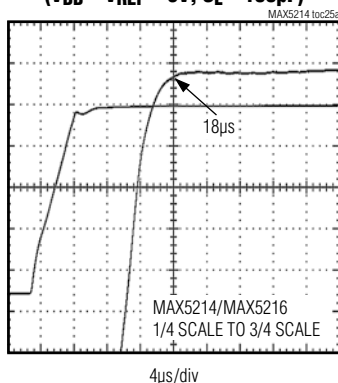
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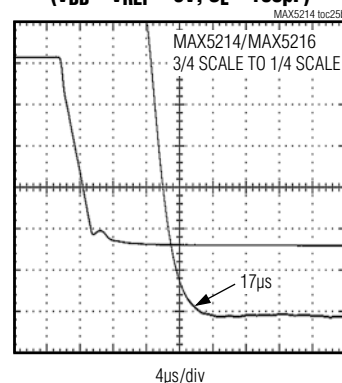
**MAJOR CODE TRANSITION
(0x1FFF TO 0x2000)**



**SETTLING TO ± 0.5 LSB 14 BIT
($V_{DD} = V_{REF} = 5\text{V}$, $C_L = 100\text{pF}$)**



**SETTLING TO ± 0.5 LSB 14 BIT
($V_{DD} = V_{REF} = 5\text{V}$, $C_L = 100\text{pF}$)**



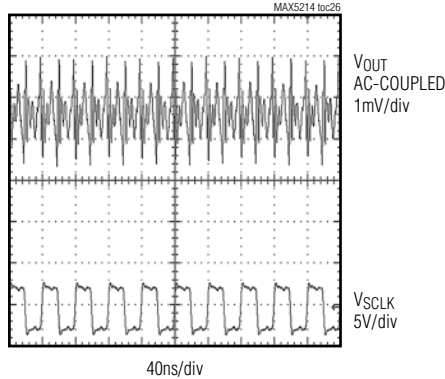
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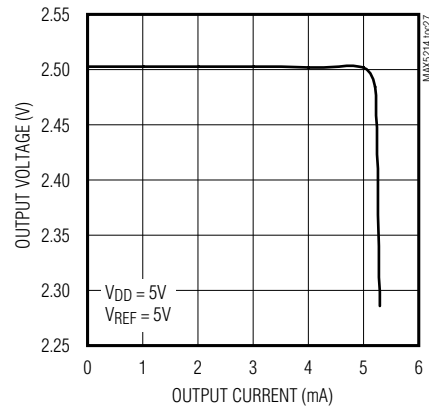
Typical Operating Characteristics (continued)

($T_A = +25^\circ\text{C}$, unless otherwise noted.)

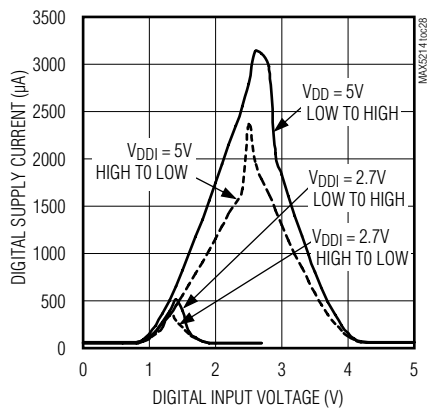
DIGITAL FEEDTHROUGH



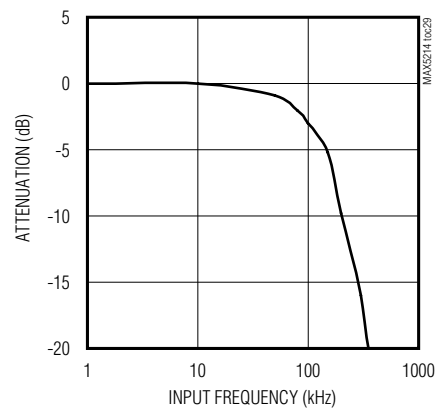
**OUTPUT VOLTAGE
vs. OUTPUT CURRENT**



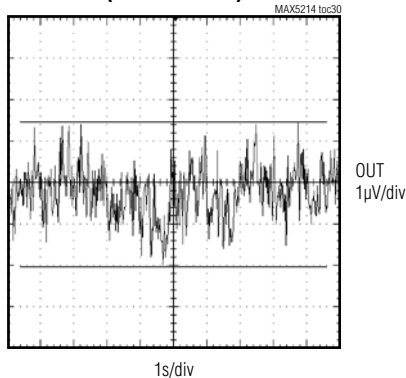
**SUPPLY CURRENT
vs. DIGITAL INPUT VOLTAGE**



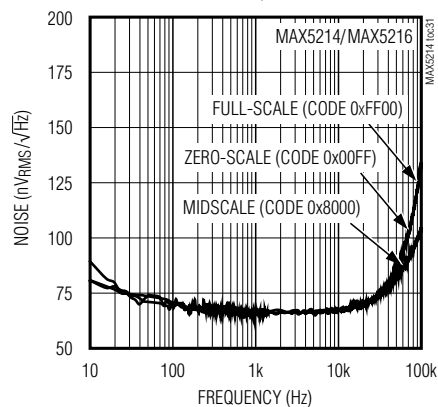
**REFERENCE INPUT BANDWIDTH
vs. FREQUENCY**



**INTEGRATED OUTPUT NOISE
(0.1Hz to 10Hz)**



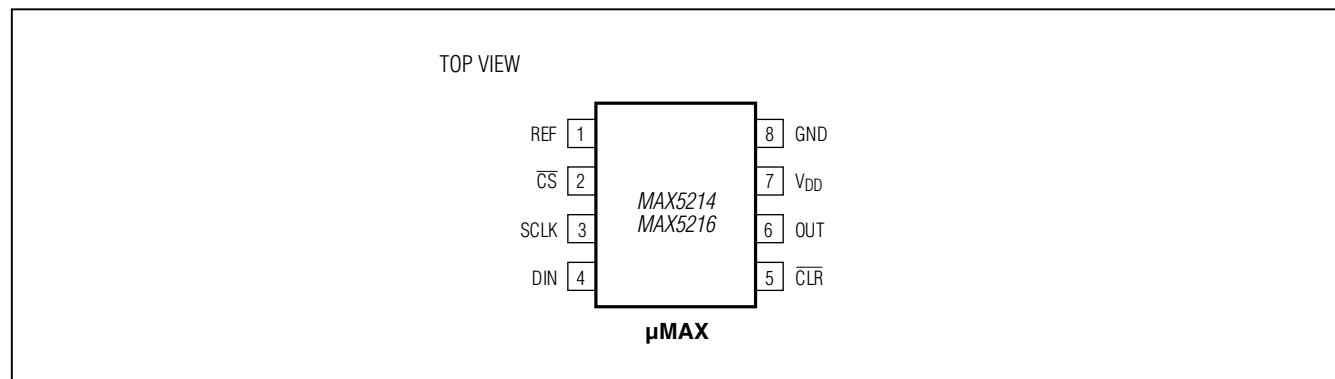
**DAC OUTPUT NOISE DENSITY
vs. FREQUENCY**



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Pin Configuration



Pin Description

PIN	NAME	FUNCTION
1	REF	Reference Voltage Input. Bypass REF with a 0.1µF capacitor to GND.
2	CS	Active-Low Chip-Select Input
3	SCLK	Serial-Clock Input
4	DIN	Data In
5	CLR	Active-Low Asynchronous Digital-Clear Input. Drive CLR low to clear the contents of the input and DAC registers and set the DAC output to zero.
6	OUT	Buffered DAC Voltage Output
7	VDD	Supply Voltage. Bypass VDD with a 0.1µF capacitor to GND.
8	GND	Ground

Detailed Description

The MAX5214/MAX5216 are pin-compatible and software-compatible 14-bit and 16-bit DACs. The MAX5214/MAX5216 are single-channel, low-power, high-reference input resistance, and buffered voltage-output DACs. The MAX5214/MAX5216 minimize the digital noise feedthrough from their inputs to their outputs by powering down the SCLK and DIN input buffers after completion of each data frame. The data frames are 16-bit for the MAX5214 and 24-bit for the MAX5216. On power-up, the MAX5214/MAX5216 reset the DAC output to zero, providing additional safety for applications that drive valves or other transducers which need to be off on power-up. The MAX5214/MAX5216 contain a segmented resistor string-type DAC, a serial-in/parallel-out shift register, a DAC register, power-on-reset (POR) circuit, CLR to asynchronously clear the device independent of the serial interface, and control logic. On the falling edge

of the clock (SCLK) pulse, the serial input (DIN) data is shifted into the device, MSB first.

Output Amplifier (OUT)

The MAX5214/MAX5216 include an internal buffer on the DAC output. The internal buffer provides improved load regulation and transition glitch suppression for the DAC output. The output buffer slews at 0.5V/µs and drives up to 10kΩ in parallel with 100pF. The analog supply voltage (VDD) determines the maximum output voltage range of the device as VDD powers the output buffer.

DAC Reference (REF)

The external reference input features a typical input impedance of 256kΩ and accepts an input voltage from +2V to VDD. Connect an external voltage supply between REF and GND to apply an external reference.

Visit www.maximintegrated.com/products/references for a list of available voltage-reference devices.

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Serial Interface

The MAX5214/MAX5216 3-wire serial interface is compatible with MICROWIRE, SPI, QSPI, and DSP. The interface provides three inputs: SCLK, $\overline{CS}$, and DIN. The chip-select input ($\overline{CS}$) frames the serial data loading at DIN. Following a chip-select input high-to-low transition, the data is shifted synchronously and latched into the input register on each falling edge of the serial-clock input (SCLK). Each serial word is 16-bit for the MAX5214 and 24-bit for the MAX5216. The first 2 bits are the control bits followed by 14 data bits (MSB first) for the MAX5214 and 22 data bits (MSB first) for the MAX5216 as shown in Tables 1 and 2. The serial input register

transfers its contents to the input registers after loading 16/24 bits of data and updates the DAC output immediately after the data is received on the 16-/24-bit falling edge of the clock. To initiate a new data transfer, drive $\overline{CS}$ high and keep $\overline{CS}$ high for a minimum of 20ns before the next write sequence. The SCLK can be either high or low between $\overline{CS}$ write pulses. Figures 1 and 2 show the timing diagram for the complete 3-wire serial interface transmission. The MAX5216 DAC code is unipolar binary with $V_{OUT} = (\text{code}/65,535) \times V_{REF}$. The MAX5214 DAC code is unipolar binary with $V_{OUT} = (\text{code}/16,383) \times V_{REF}$. See Tables 1 and 2.

Table 1. Operating Mode Truth Table (MAX5214)

16-BIT WORD																FUNCTION
CONTROL BITS		DATA BITS														
MSB		LSB														
D15	D14	D13	D12	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	
0	0	X	X	X	X	X	X	X	X	X	X	X	X	X	X	No operation
1	0	0	X	A1	A0	X	X	X	X	X	X	X	X	X	X	Power-down (see Table 3)
0	1	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0	Write through
1	1	Reserved, Do Not Use														

Table 2. Operating Mode Truth Table (MAX5216)

24-BIT WORD																		FUNCTION	
CONTROL BITS		DATA BITS																	
MSB		LSB																	
D23	D22	D21	D20	D19	D18	D17	D16	D15	D14	D13	D12	D11	D10	D9	D8	D7	D6		D5–D0
0	0	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	No operation
1	0	0	X	A1	A0	X	X	X	X	X	X	X	X	X	X	X	X	X	Power-down (see Table 3)
0	1	B15	B14	B13	B12	B11	B10	B9	B8	B7	B6	B5	B4	B3	B2	B1	B0	X	Write through
1	1	Reserved, Do Not Use																	

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Writing to the Devices

- 1) Drive $\overline{CS}$ low, enabling the shift register.
- 2) Clock 16/24 bits of data into DIN (MSB first and LSB last), observing the specified setup and hold times.
- 3) After clocking in the last data bit, drive $\overline{CS}$ high. $\overline{CS}$ must remain high for 20ns before the next transmission is started.

Figure 1 shows a write operation for the transmission of 16 bits. If $\overline{CS}$ is driven high at any point prior to receiving 16 bits, the transmission is discarded.

Figure 2 shows a write operation for the transmission of 24 bits. If $\overline{CS}$ is driven high at any point prior to receiving 24 bits, the transmission is discarded.

Clear ($\overline{CLR}$)

The MAX5214/MAX5216 feature an asynchronous active-low $\overline{CLR}$ logic input that sets the DAC output to zero. Driving $\overline{CLR}$ low clears the contents of both the input and DAC registers and also aborts the on-going SPI command. To allow a new SPI command, drive $\overline{CLR}$ high.

Power-Down Mode

The MAX5214/MAX5216 feature a software-controlled power-down mode. In power-down, the output disconnects from the buffer and is grounded with one of the three selectable internal resistors. See Table 3 for the selectable internal resistor values in power-down mode. The selected mode takes effect on the 16th SCLK falling edge of the MAX5214 and 24th SCLK falling edge of the MAX5216. The serial interface remains active in power-down mode. In order to abort the power-down mode selection, pull $\overline{CS}$ high prior to the 16th (MAX5214) or 24th (MAX5216) SCLK falling edge. The contents of the DAC register remain valid while in power-down mode, allowing for the DAC to return to previous code by writing 0x8000 for the MAX5214 or 0x800000 for the MAX5216 (Table 3). A write to the write-through register causes the device to immediately exit power-down mode and transition to the requested code (see Tables 1 and 2).

Table 3. Power-Down Modes

A1	A0	DESCRIPTION	DAC OPERATION CONDITION
0	0	DAC powers up and returns to its previous code setting.	Normal operation
0	1	DAC powers down; OUT is high impedance.	Power-down
1	0	DAC powers down; OUT connects to ground through an internal 100k Ω resistor.	
1	1	DAC powers down; OUT connects to ground through an internal 1k Ω resistor.	

Table 4. MAX5216 Input Code vs. Output Voltage

DAC LATCH CONTENTS	ANALOG OUTPUT (V _{out})
MSB → LSB	
1111 1111 1111 1111	$V_{REF} \times (65,535/65,535)$
1000 0000 0000 0000	$V_{REF} \times (32,768/65,535) = 1/2 V_{REF}$
0000 0000 0000 0001	$V_{REF} \times (1/65,535)$
0000 0000 0000 0000	0V

Table 5. MAX5214 Input Code vs. Output Voltage

DAC LATCH CONTENTS	ANALOG OUTPUT (V _{out})
MSB → LSB	
1111 1111 1111 11XX	$V_{REF} \times (16,383/16,383)$
1000 0000 0000 00XX	$V_{REF} \times (8,192/16,383) = 1/2 V_{REF}$
0000 0000 0000 01XX	$V_{REF} \times (1/16,383)$
0000 0000 0000 00XX	0V

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Applications Information

Power-On Reset (POR)

When first power is applied to V_{DD} , the input registers are set to zero so the DAC output is set to code zero. To optimize DAC linearity, wait until the supplies have settled. The MAX5214/MAX5216 output voltage range is 0 to V_{REF} .

Power Supplies and Bypassing Considerations

Bypass V_{DD} with high-quality 0.1 μ F ceramic capacitors to a low-impedance ground as close as possible to the device.

Minimize lead lengths to reduce lead inductance. Connect the GND to the analog ground plane.

Layout Considerations

Digital and AC transient signals on GND can create noise at the output. Connect GND to the star ground for the DAC system. Refer the remote DAC loads to this system ground for the best possible performance. Use proper grounding techniques, such as a multilayer board with a low-inductance ground plane, or star connect all ground return paths back to the MAX5214/MAX5216 GND. Carefully lay out the traces between channels to reduce AC cross-coupling. Do not use wire-wrapped boards and sockets. Use shielding to improve noise immunity. Do not run analog and digital signals parallel to one another, especially clock signals. Avoid routing digital lines underneath the MAX5214/MAX5216 package.

Definitions

Integral Nonlinearity (INL)

INL is the deviation of the measured transfer function from a straight line drawn between two codes once offset and gain errors have been nullified.

Differential Nonlinearity (DNL)

DNL is the difference between an actual step height and the ideal value of 1 LSB. If the magnitude of the DNL is greater than -1 LSB, the DAC guarantees no missing codes and is monotonic.

Offset Error

Offset error indicates how well the actual transfer function matches the ideal transfer function at a single point.

Typically, the point at which the offset error is specified is at or near the zero-scale point of the transfer function.

Gain Error

Gain error is the difference between the ideal and the actual full-scale output voltage on the transfer curve, after nullifying the offset error. This error alters the slope of the transfer function and corresponds to the same percentage error in each step.

Settling Time

The settling time is the amount of time required from the start of a transition, until the DAC output settles to the new output value within the converter's specified accuracy.

Digital Feedthrough

Digital feedthrough is the amount of noise that appears on the DAC output when the DAC digital control lines are toggled.

Digital-to-Analog Glitch Impulse

A major carry transition occurs at the midscale point where the MSB changes from low to high and all other bits change from high to low, or where the MSB changes from high to low and all other bits change from low to high. The duration of the magnitude of the switching glitch during a major carry transition is referred to as the digital-to-analog glitch impulse.

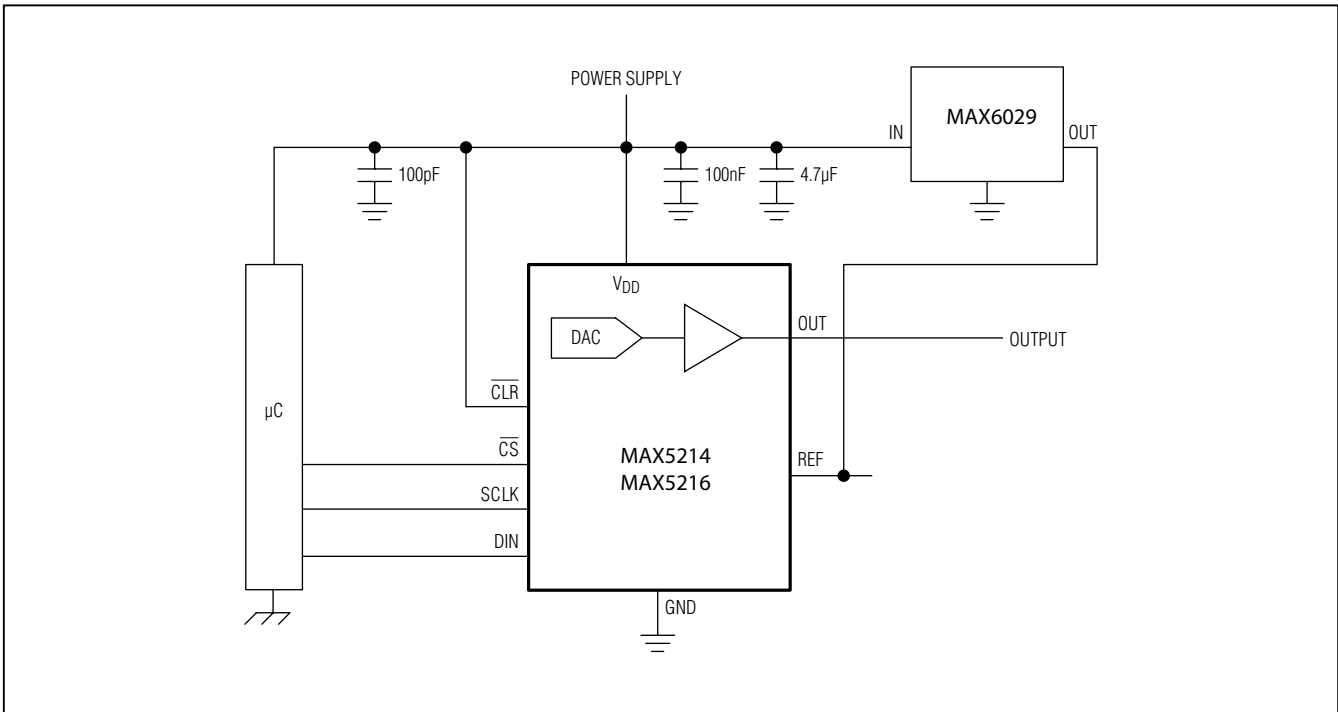
Digital-to-Analog Power-Up Glitch Impulse

The digital-to-analog power-up glitch is the duration of the magnitude of the switching glitch that occurs as the device exits power-down mode.

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Typical Operating Circuit



Chip Information

PROCESS: BiCMOS

Ordering Information

PART	PIN- PACKAGE	RESOLUTION (BITS)	INL MAX (LSB)
MAX5214GUA+	8 μMAX	14	±1
MAX5216GUA+	8 μMAX	16	±4
MAX5216BGUA+	8 μMAX	16	±8

Note: All devices are specified over the -40°C to +105°C operating temperature range.

+Denotes a lead(Pb)-free/RoHS-compliant package.

Package Information

For the latest package outline information and land patterns, go to www.maximintegrated.com/packages. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	OUTLINE NO.	LAND PATTERN NO.
8 μMAX	U8+3	21-0036	90-0092

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Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	12/10	Initial release	—
1	6/13	Added an additional electrical grade for MAX5216. Made multiple text edits and updated the <i>Typical Operating Characteristics</i> .	1–17
2	7/13	Updated <i>General Description</i> , <i>Features</i> , and the <i>Electrical Characteristics</i> .	1, 3



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