



- Compact design
- Analog output voltage/current
- Non-contact
- High repeat accuracy
- High temperature stability
- High linearity
- Magnet sensing (AMD0..., EMD0...)

### Safety Advisory



This analog position sensor is not permitted for use in applications where personal safety depends on proper function of the device (not a safety component according to the EC Machine Directive). Read this manual carefully before using the sensor.

### Function Principles

The magneto-inductive linear position sensors are non-contacting. They use a permanent magnet element and sense the change in inductance of a coil induced by this magnetic element. The processing circuitry is built-in, providing an absolute and distance-proportional voltage or current signal of 0...10V or 4...20 mA / 0...20 mA. They are characterized by high repeat accuracy, temperature stability and linearity.

Their versatility, ruggedness and compact design make them standouts for numerous industrial applications. Thanks to their fully analog principles of operation, they are ideal for control and feedback tasks.

The versions with magnet sensing indicate when the position magnet has left the working range. Their unique characteristic output curve makes them ideal for applications in which only part of a motion needs to be detected.

In addition to the recommended position magnets, already existing permanent magnets can often be used (such as found in pneumatic cylinders).

Typical applications range from handling and robotics to conveying and building technology to metering and flow measurement.

U.S. Patent No. 6,714,004

### Model Overview

| BIL Standard                                                            | Output     |
|-------------------------------------------------------------------------|------------|
| • Working range 30 mm<br>BIL ED0-T030A-01-S75                           | V / I      |
| • Working range 60 mm<br>BIL AD0-P060A-01-S75<br>BIL ED0-P060A-01-S75   | V<br>V / I |
| • Working range 160 mm<br>BIL ED0-P160A-01-S75                          | V / I      |
| BIL with magnet sensing                                                 | Output     |
| • Working range 60 mm<br>BIL AMD0-T060A-01-S75<br>BIL EMD0-T060A-01-S75 | V<br>V / I |

### Position Magnets

#### Standard models

- BIL 000-MH-A
- BIL 001-MH-A

Other position magnets on request

See page 8 for installation instructions

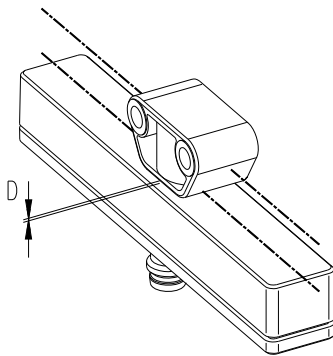
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balluff@balluff.de  
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# User's Manual

## Inductive Analog Position Sensor BIL SmartSens

### Assembly

When assembling the BIL sensor and position magnet, note the requirement for collinear orientation of the center axes and observe distance D between the sensor and position magnet. Refer to Assembly diagram 1. The supplied mounting brackets and screws are recommended for installing the BIL sensor system, since their design and material guarantee minimal distortion of the output curve.



Assembly diagram 1

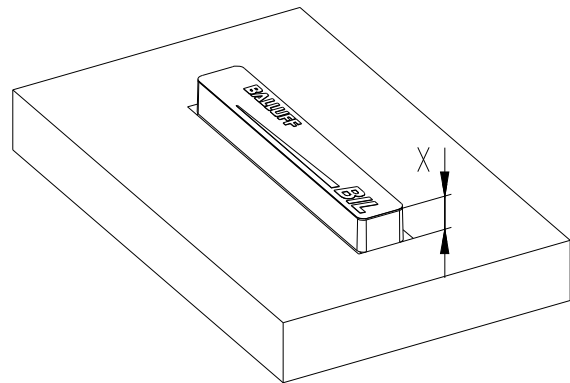
### Installation Instructions

Installing in or on metallic surfaces will – depending on the material properties – result in slight effects on the characteristic parameters. In general, non-magnetizable materials such as alloys, austenitic steels, plastics, etc. are recommended. This applied both to the sensor and the position magnet.

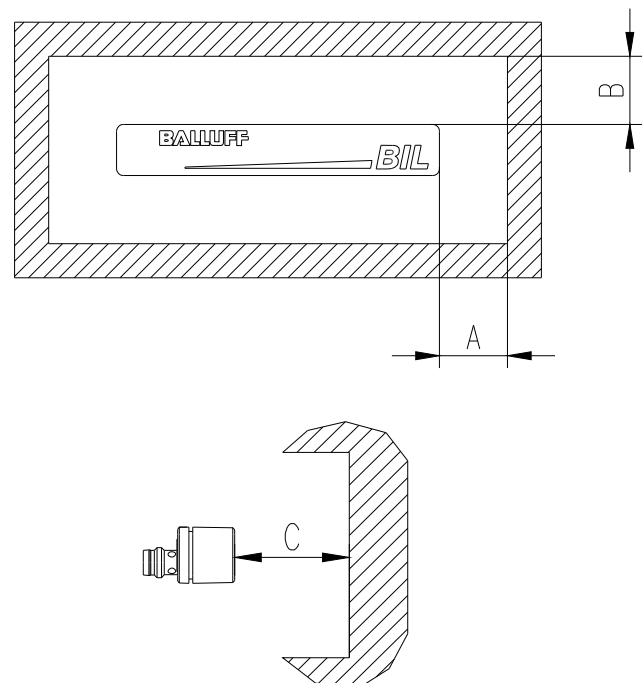
Magnetizable materials (ferrous) affect the geometry and strength of the effective field of the position magnet, and can themselves become magnetized by the motion of the position magnet; this in turn will affect the characteristic parameters in the same way that any nearby magnetic field would.

The sensor may be flush mounted in non-magnetizable metallic material. This will slightly increase the full scale of the output signal. This effect is reduced by increasing distance X (see Installation diagram 1).

The following pages show the recommended distances A, B and C from magnetizable materials for each sensor model (please refer to Installation diagram 2).



Installation diagram 1



Installation diagram 2

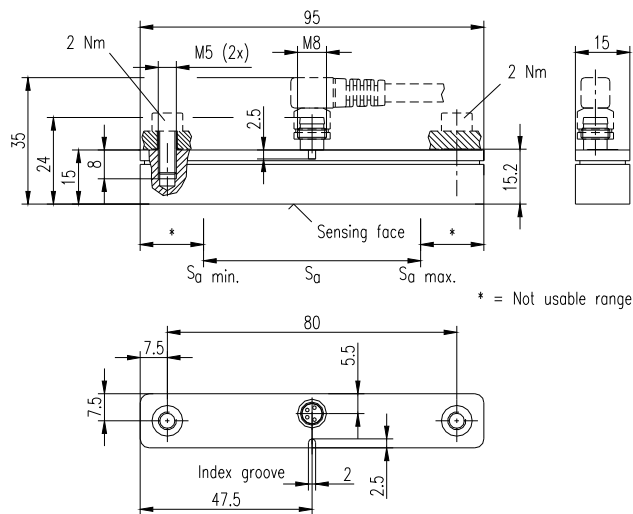
### Materials between Sensor and Position Magnet

The sensing principle allows the position magnet to be detected through solid materials (such as glass, light metals, plastics, austenitic steels) without causing noticeable changes in the dynamic properties. As with the installation materials, the characteristic curve may be affected by the material properties. Possible areas of application here include valves, cylinders, level meters, etc.

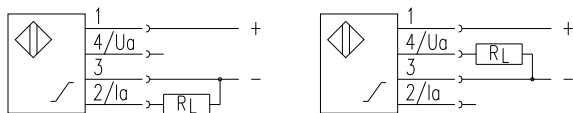
It is not possible to sense through magnetizable (ferrous) materials.

# Inductive Analog Position Sensor BIL ED0-T030A-01-S75

## Product View

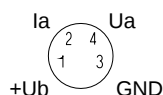


## Connection Diagram

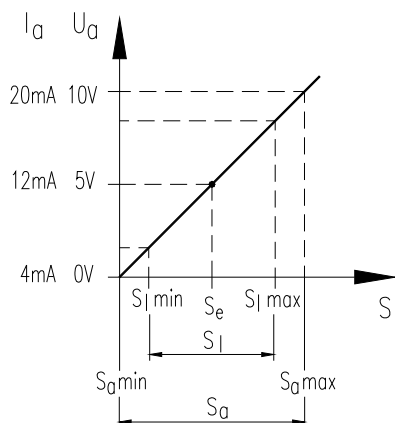


Do not use current and voltage output simultaneously.

## Pin Configuration



## Characteristic Curve



## Technical Data

### Characteristic Data

|                                 |                       |            |
|---------------------------------|-----------------------|------------|
| Working range $s_a$             | [mm]                  | 0...30     |
| Linear range $s_l$              | [mm]                  | 0...30     |
| Rated operating distance $s_e$  | [mm]                  | 15         |
| Linearity error at $s_l$        | [mm]                  | $\pm 0,3$  |
| Repeat accuracy $R_{NORM}$      | [% v. $I_a/U_a$ max.] | $\leq 0.1$ |
| Repeat accuracy $R_{BWN} 1)$    | [ $\mu m$ ]           | $\pm 30$   |
| Ambient temperature $T_A$       | [°C]                  | -10...+70  |
| Optimum working temperature     | [°C]                  | +10...+50  |
| Max. temperature drift at $s_l$ | [%]                   | $\pm 2,5$  |

### Electrical Data

|                                                       |              |                                     |
|-------------------------------------------------------|--------------|-------------------------------------|
| Effective operating voltage $U_e$                     | [V]          | 24                                  |
| Supply voltage $U_B$                                  | [V]          | 10...30 / 15...30                   |
| Load resistance $R_L$ max. ( $I_a$ ) / min. ( $U_a$ ) | [ $\Omega$ ] | 500 / 2000                          |
| No-load current $I_0$ at $U_e$                        | [mA]         | $\leq 30$                           |
| Protected against any wire reversal                   |              | <input checked="" type="checkbox"/> |
| Reverse polarity protected                            |              | <input checked="" type="checkbox"/> |

## Optical Indicators

|                         |   |
|-------------------------|---|
| Supply voltage          | - |
| Position magnet sensing | - |

### Mechanical Data

|                  |                          |
|------------------|--------------------------|
| Housing material | PA fiberglass reinforced |
| Enclosure rating | IP 67                    |

## Installation Dimensions

|   |      |    |
|---|------|----|
| A | [mm] | 50 |
| B | [mm] | 50 |
| C | [mm] | 50 |

### Remarks

The rated operating distance  $s_e$  specifies the center of the measuring range. It is indicated on the sensor by an index notch.

- 1) Measuring conditions:  $U_e = 24V$ ,  $R_L = 500 \Omega / 10 k\Omega$  (I/U),  
measured after 15 min. at the index point  $s_e$

The characteristic data are only valid within the defined working range  $s_a$  at distance D from the respective position magnet.

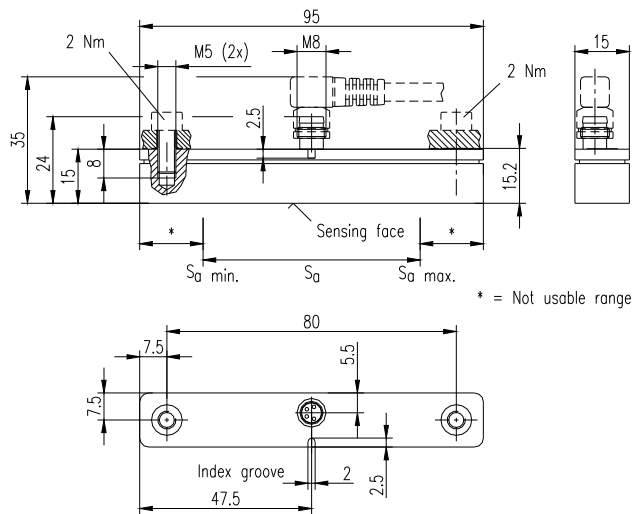
Unless otherwise indicated all values are in accordance with IEC 60947-5-7, Balluff Factory Standard BWN PR. 44

For NFPA 79 applications only (machines with a supply voltage of less than 600 volts).

Appropriate connectors can be obtained from Balluff.

# Inductive Analog Position Sensor BIL AD0-P060A-01-S75

## Product View



## Technical Data

### Characteristic Data

|                                 |                   |            |
|---------------------------------|-------------------|------------|
| Working range $s_a$             | [mm]              | 0...60     |
| Linear range $s_l$              | [mm]              | 5...55     |
| Rated operating distance $s_e$  | [mm]              | 30         |
| Linearity error at $s_l$        | [mm]              | 0,6        |
| Repeat accuracy $R_{NORM}$      | [% v. $U_a$ max.] | $\leq 0,1$ |
| Repeat accuracy $R_{BWN 1)$     | [ $\mu m$ ]       | $\pm 60$   |
| Ambient temperature $T_A$       | [°C]              | -10...+75  |
| Optimum working temperature     | [°C]              | +10...+50  |
| Max. temperature drift at $s_l$ | [%]               | $\pm 2$    |

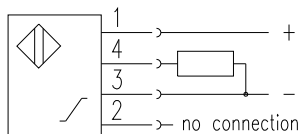
### Electrical Data

|                                     |              |                                     |
|-------------------------------------|--------------|-------------------------------------|
| Effective operating voltage $U_e$   | [V]          | 24                                  |
| Supply voltage $U_B$                | [V]          | 15...30                             |
| Load resistance $R_L$ min.          | [ $\Omega$ ] | 2000                                |
| No-load current $I_0$ at $U_e$      | [mA]         | $\leq 30$                           |
| Protected against any wire reversal |              | <input checked="" type="checkbox"/> |
| Reverse polarity protected          |              | <input checked="" type="checkbox"/> |

### Optical Indicators

|                         |   |
|-------------------------|---|
| Supply voltage          | - |
| Position magnet sensing | - |

## Connection Diagram



### Mechanical Data

|                  |                          |
|------------------|--------------------------|
| Housing material | PA fibreglass reinforced |
| Enclosure rating | IP 67                    |

### Installation Dimensions

|   |      |    |
|---|------|----|
| A | [mm] | 50 |
| B | [mm] | 50 |
| C | [mm] | 50 |

### Remarks

The rated operating distance  $s_e$  specifies the center of the measuring range. It is indicated on the sensor by an index notch.

- 1) Measuring conditions:  $U_e = 24V$ ,  $10 k\Omega$ ,  
measured after 15 min. at the index point  $s_e$

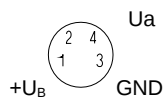
The characteristic data are only valid within the defined working range  $s_a$  at distance  $D$  from the respective position magnet.

Unless otherwise indicated all values are in accordance with IEC 60947-5-7, Balluff Factory Standard BWN PR. 44

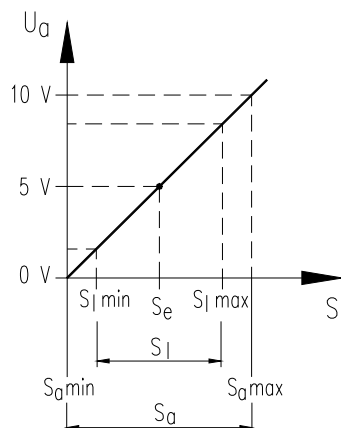
For NFPA 79 applications only (machines with a supply voltage of less than 600 volts).

Appropriate connectors can be obtained from Balluff.

## Pin Configuration

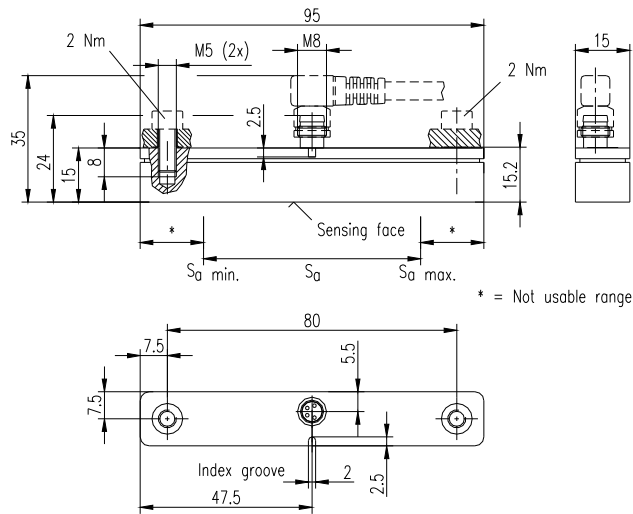


## Characteristic Curve

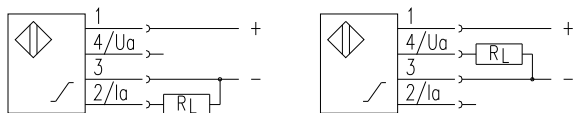


# Inductive Analog Position Sensor BIL ED0-P060A-01-S75

## Product View

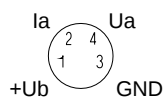


## Connection Diagram

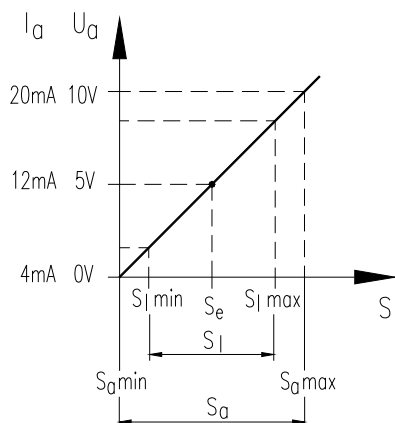


Do not use current and voltage output simultaneously.

## Pin Configuration



## Characteristic Curve



## Technical Data

### Characteristic Data

|                                 |                       |            |
|---------------------------------|-----------------------|------------|
| Working range $s_a$             | [mm]                  | 0...60     |
| Linear range $s_l$              | [mm]                  | 5...55     |
| Rated operating distance $s_e$  | [mm]                  | 30         |
| Linearity error at $s_l$        | [mm]                  | 0.6        |
| Repeat accuracy $R_{NORM}$      | [% v. $I_a/U_a$ max.] | $\leq 0.1$ |
| Repeat accuracy $R_{BWN 1)$     | [ $\mu m$ ]           | $\pm 60$   |
| Ambient temperature $T_A$       | [°C]                  | -10...+75  |
| Optimum working temperature     | [°C]                  | +10...+50  |
| Max. temperature drift at $s_l$ | [%]                   | $\pm 2$    |

### Electrical Data

|                                                       | $I_a / U_a$                         |
|-------------------------------------------------------|-------------------------------------|
| Effective operating voltage $U_e$                     | [V] 24                              |
| Supply voltage $U_B$                                  | [V] 10...30 / 15...30               |
| Load resistance $R_L$ max. ( $I_a$ ) / min. ( $U_a$ ) | [ $\Omega$ ] 500 / 2000             |
| No-load current $I_0$ at $U_e$                        | [mA] $\leq 30$                      |
| Protected against any wire reversal                   | <input checked="" type="checkbox"/> |
| Reverse polarity protected                            | <input checked="" type="checkbox"/> |

### Optical Indicators

|                         |   |
|-------------------------|---|
| Supply voltage          | - |
| Position magnet sensing | - |

### Mechanical Data

|                  |                          |
|------------------|--------------------------|
| Housing material | PA fiberglass reinforced |
| Enclosure rating | IP 67                    |

### Installation Dimensions

|   |      |    |
|---|------|----|
| A | [mm] | 50 |
| B | [mm] | 50 |
| C | [mm] | 50 |

### Remarks

The rated operating distance  $s_e$  specifies the center of the measuring range. It is indicated on the sensor by an index notch.

- 1) Measuring conditions:  $U_e = 24V$ ,  $R_L = 500 \Omega / 10 k\Omega (I/U)$ , measured after 15 min. at the index point  $s_e$

The characteristic data are only valid within the defined working range  $s_a$  at distance  $D$  from the respective position magnet.

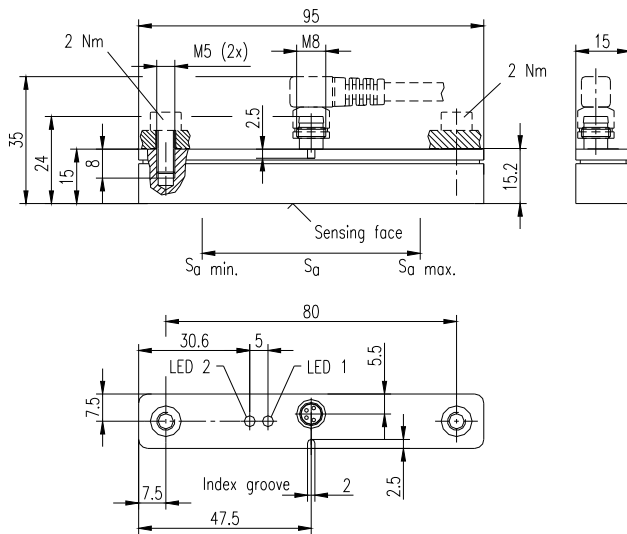
Unless otherwise indicated all values are in accordance with IEC 60947-5-7, Balluff Factory Standard BWN PR. 44

For NFPA 79 applications only (machines with a supply voltage of less than 600 volts).

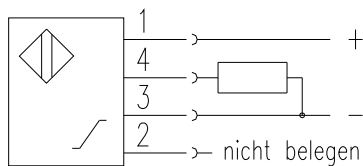
Appropriate connectors can be obtained from Balluff.

# Inductive Analog Position Sensor BIL AMD0-T060A-01-S75

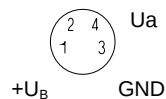
## Product View



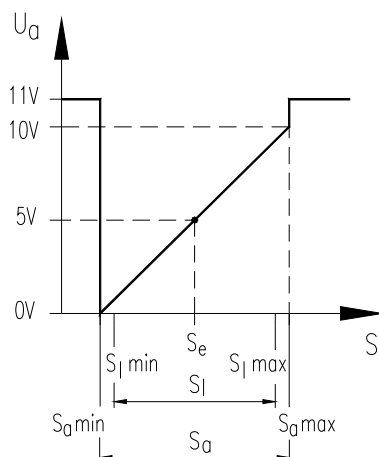
## Connection Diagram



## Pin Configuration



## Characteristic Curve



## Position Magnet Sensing

The BIL AMD0 is capable of position magnet sensing. If the position magnet is outside the working range, this is indicated in two ways:

- The output signal rises to typ.  
 $U_a = 11 \text{ V}$
- LED 2 comes on

## Technical Data

### Characteristic Data

|                                    |                                |            |
|------------------------------------|--------------------------------|------------|
| Working range $s_a$                | [mm]                           | 0...60     |
| Linear range $s_l$                 | [mm]                           | 5...55     |
| Rated operating distance $s_e$     | [mm]                           | 30         |
| Linearity error at $s_l$           | [mm]                           | 1          |
| Repeat accuracy $R_{\text{NORM}}$  | [% v. $I_a/U_a \text{ max.}$ ] | $\leq 0,5$ |
| Repeat accuracy $R_{\text{BWN 1)}$ | [ $\mu\text{m}$ ]              | $\pm 60$   |
| Ambient temperature $T_A$          | [ $^{\circ}\text{C}$ ]         | -10...+75  |
| Optimum working temperature        | [ $^{\circ}\text{C}$ ]         | +10...+50  |
| Max. temperature drift at $s_l$    | [%]                            | $\pm 2,5$  |

### Electrical Data

|                                                            |              |                                     |
|------------------------------------------------------------|--------------|-------------------------------------|
| Effective operating voltage $U_e$                          | [V]          | 24                                  |
| Supply voltage $U_B$                                       | [V]          | 15...30                             |
| Load resistance $R_L \text{ max.}(I_a) / \text{min.}(U_a)$ | [ $\Omega$ ] | 2000                                |
| No-load current $I_0$ at $U_e$                             | [mA]         | $\leq 30$                           |
| Protected against any wire reversal                        |              | <input checked="" type="checkbox"/> |
| Reverse polarity protected                                 |              | <input checked="" type="checkbox"/> |

### Optical Indicators

|                         |       |
|-------------------------|-------|
| Supply voltage          | LED 1 |
| Position magnet sensing | LED 2 |

### Mechanical Data

|                  |                          |
|------------------|--------------------------|
| Housing material | PA fibreglass reinforced |
| Enclosure rating | IP 67                    |

### Installation Dimensions

|   |      |    |
|---|------|----|
| A | [mm] | 50 |
| B | [mm] | 50 |
| C | [mm] | 50 |

### Remarks

The rated operating distance  $s_e$  specifies the center of the measuring range. It is indicated on the sensor by an index notch.

- Measuring conditions:  $U_e = 24 \text{ V}$ ,  $R_L = 10 \text{ k}\Omega$ , measured after 15 min. at the index point  $s_e$

The characteristic data are only valid within the defined working range  $s_a$  at distance  $D$  from the respective position magnet.

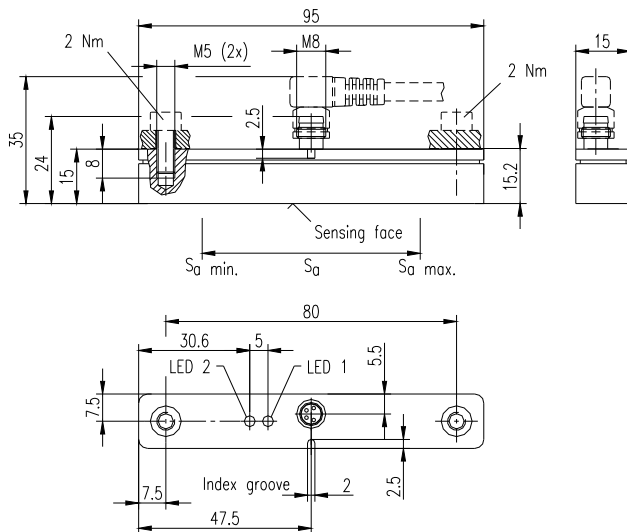
Unless otherwise indicated all values are in accordance with IEC 60947-5-7, Balluff Factory Standard BWN PR. 44

For NFPA 79 applications only (machines with a supply voltage of less than 600 volts).

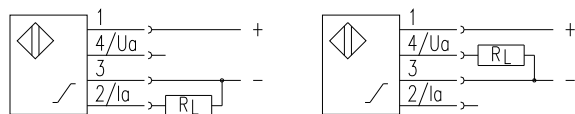
Appropriate connectors can be obtained from Balluff.

# Inductive Analog Position Sensor BIL EMD0-T060A-01-S75

## Product View

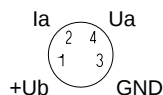


## Connection Diagram

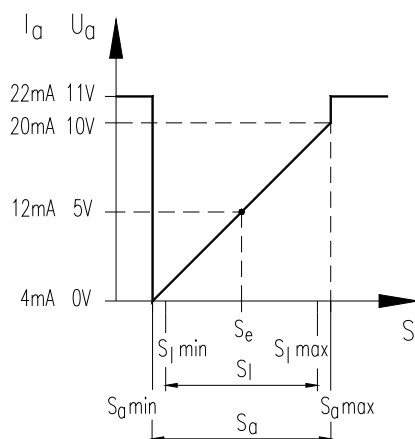


Do not use current and voltage output simultaneously.

## Pin Configuration



## Characteristic Curve



## Position Magnet Sensing

The BIL EMD0 is capable of position magnet sensing. If the position magnet is outside the working range, this is indicated in two ways:

- The output signal rises to typ.  
 $I_a = 22 \text{ mA} / U_a = 11 \text{ V}$
- LED 2 comes on

## Technical Data

### Characteristic Data

|                                    |                                |            |
|------------------------------------|--------------------------------|------------|
| Working range $s_a$                | [mm]                           | 0...60     |
| Linear range $s_l$                 | [mm]                           | 5...55     |
| Rated operating distance $s_e$     | [mm]                           | 30         |
| Linearity error at $s_l$           | [mm]                           | 1          |
| Repeat accuracy $R_{\text{NORM}}$  | [% v. $I_a/U_a \text{ max.}$ ] | $\leq 0,5$ |
| Repeat accuracy $R_{\text{BWN 1)}$ | [ $\mu\text{m}$ ]              | $\pm 60$   |
| Ambient temperature $T_A$          | [°C]                           | -10...+75  |
| Optimum working temperature        | [°C]                           | +10...+50  |
| Max. temperature drift at $s_l$    | [%]                            | $\pm 2,5$  |

### Electrical Data

|                                                            |                                     |
|------------------------------------------------------------|-------------------------------------|
|                                                            | $I_a / U_a$                         |
| Effective operating voltage $U_e$                          | [V] 24                              |
| Supply voltage $U_B$                                       | [V] 10...30 / 15...30               |
| Load resistance $R_L \text{ max.}(I_a) / \text{min.}(U_a)$ | [ $\Omega$ ] 500 / 2000             |
| No-load current $I_0$ at $U_e$                             | [mA] $\leq 30$                      |
| Protected against any wire reversal                        | <input checked="" type="checkbox"/> |
| Reverse polarity protected                                 | <input checked="" type="checkbox"/> |

### Optical Indicators

|                         |       |
|-------------------------|-------|
| Supply voltage          | LED 1 |
| Position magnet sensing | LED 2 |

### Mechanical Data

|                  |                          |
|------------------|--------------------------|
| Housing material | PA fibreglass reinforced |
| Enclosure rating | IP 67                    |

### Installation Dimensions

|   |      |    |
|---|------|----|
| A | [mm] | 50 |
| B | [mm] | 50 |
| C | [mm] | 50 |

### Remarks

The rated operating distance  $s_e$  specifies the center of the measuring range. It is indicated on the sensor by an index notch.

- Measuring conditions:  $U_e = 24 \text{ V}$ ,  $R_L = 500 \Omega / 10 \text{ k}\Omega$  (I/U), measured after 15 min. at the index point  $s_e$

The characteristic data are only valid within the defined working range  $s_a$  at distance D from the respective position magnet.

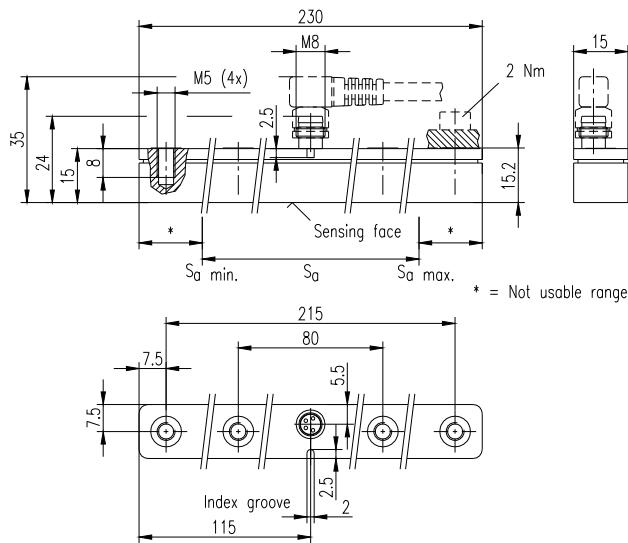
Unless otherwise indicated all values are in accordance with IEC 60947-5-7, Balluff Factory Standard BWN PR. 44

For NFPA 79 applications only (machines with a supply voltage of less than 600 volts).

Appropriate connectors can be obtained from Balluff.

# Inductive Analog Position Sensor BIL ED0-P160A-01-S75

## Product View



## Technical Data

### Characteristic Data

|                                 |                       |            |
|---------------------------------|-----------------------|------------|
| Working range $s_a$             | [mm]                  | 0...160    |
| Linear range $s_l$              | [mm]                  | 0...160    |
| Rated operating distance $s_e$  | [mm]                  | 80         |
| Linearity error at $s_l$        | [mm]                  | 2.4        |
| Repeat accuracy $R_{NORM}$      | [% v. $I_a/U_a$ max.] | $\leq 0.3$ |
| Repeat accuracy $R_{BWN 1)$     | [ $\mu$ m]            | $\pm 500$  |
| Ambient temperature $T_A$       | [°C]                  | -10...+75  |
| Optimum working temperature     | [°C]                  | +10...+50  |
| Max. temperature drift at $s_l$ | [%]                   | $\pm 3$    |

### Electrical Data

|                                                       | $I_a / U_a$                         |
|-------------------------------------------------------|-------------------------------------|
| Effective operating voltage $U_e$                     | [V] 24                              |
| Supply voltage $U_B$                                  | [V] 10...30 / 15...30               |
| Load resistance $R_L$ max. ( $I_a$ ) / min. ( $U_a$ ) | [ $\Omega$ ] 500 / 2000             |
| No-load current $I_0$ at $U_e$                        | [mA] $\leq 25$                      |
| Protected against any wire reversal                   | <input checked="" type="checkbox"/> |
| Reverse polarity protected                            | <input checked="" type="checkbox"/> |

### Optical Indicators

|                         |   |
|-------------------------|---|
| Supply voltage          | - |
| Position magnet sensing | - |

### Mechanical Data

|                  |                          |
|------------------|--------------------------|
| Housing material | PA fibreglass reinforced |
| Enclosure rating | IP 67                    |

### Installation Dimensions

|   |      |    |
|---|------|----|
| A | [mm] | 50 |
| B | [mm] | 50 |
| C | [mm] | 50 |

### Remarks

The rated operating distance  $s_e$  specifies the center of the measuring range. It is indicated on the sensor by an index notch.

- 1) Measuring conditions:  $U_e = 24V$ ,  $R_L = 500 \Omega / 10 k\Omega (I/U)$ , measured after 15 min. at the index point  $s_e$

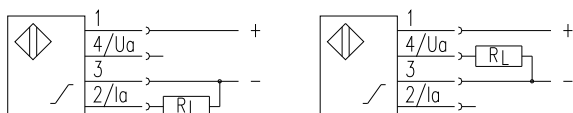
The characteristic data are only valid within the defined working range  $s_a$  at distance  $D$  from the respective position magnet.

Unless otherwise indicated all values are in accordance with IEC 60947-5-7, Balluff Factory Standard BWN PR. 44

For NFPA 79 applications only (machines with a supply voltage of less than 600 volts).

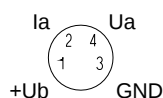
Appropriate connectors can be obtained from Balluff.

## Connection Diagram

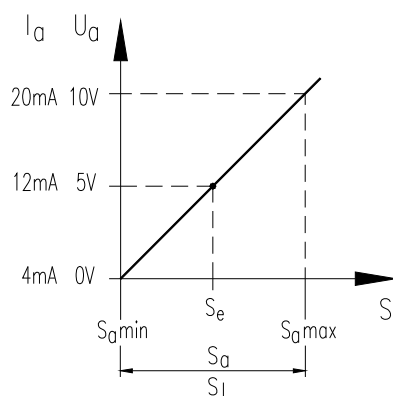


Do not use current and voltage output simultaneously.

## Pin Configuration



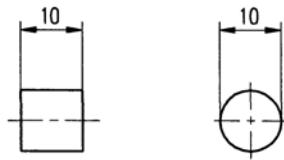
## Characteristic Curve



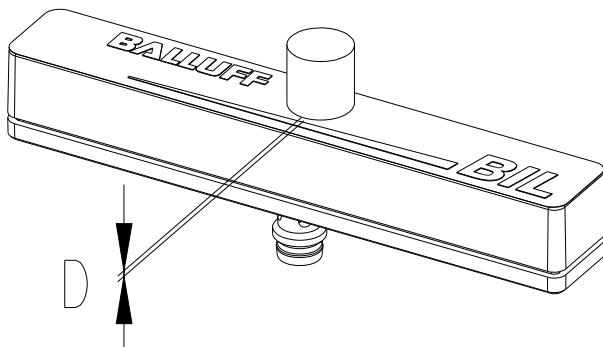
# Position Magnets BIL SmartSens

## BIL 000-MH-A

### Product view



### Installation Instructions



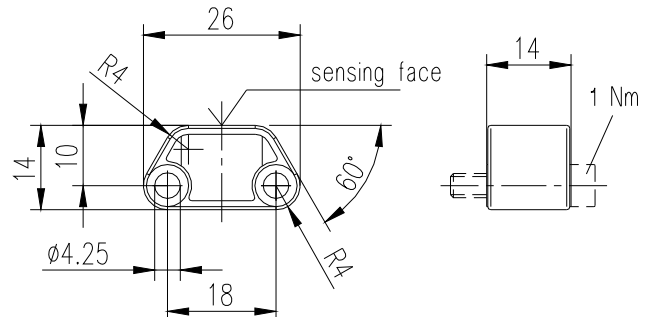
BIL 000-MH-A on BIL

### Characteristic Data

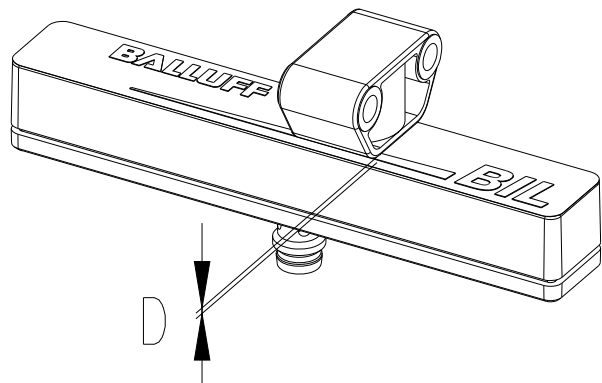
|                     |      |              |
|---------------------|------|--------------|
| Distance D          | [mm] | 2            |
| Ambient temperature | [°C] | -25...+100   |
| Material            |      | Hard ferrite |
| Weight              | [g]  | 5            |

## BIL 001-MH-A

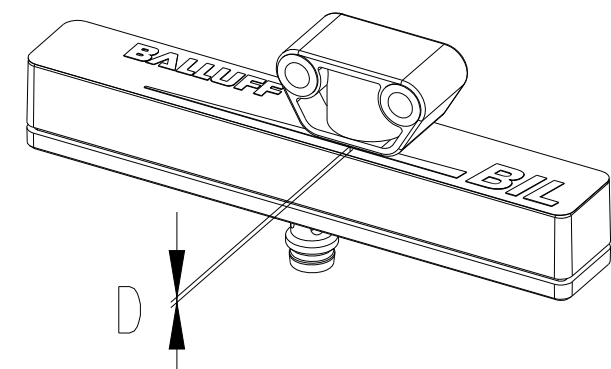
### Product view



### Installation Instructions



BIL 001-MH-A mounted lateral to center axis.



BIL 001-MH-A mounted axial to center axis.

### Characteristic Data

|                     |      |                          |
|---------------------|------|--------------------------|
| Distance D          | [mm] | 1                        |
| Ambient temperature | [°C] | -25...+100               |
| Material            |      | PA fibreglass reinforced |
| Weight              | [g]  | 8                        |

