



A New Direction in Mixed-Signal

# KH232

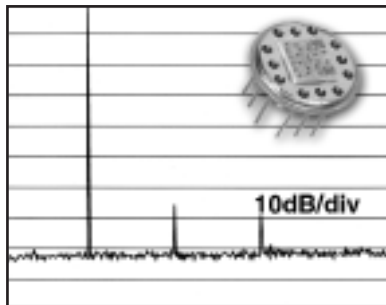
## Low Distortion Wideband Op Amp

### Features

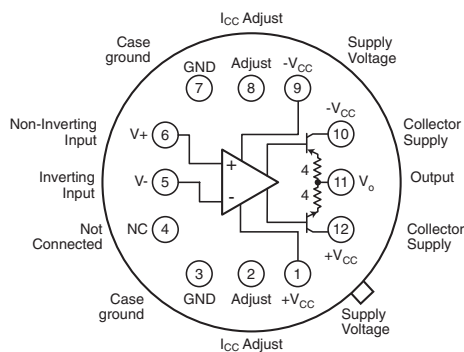
- -69dBc 2nd and 3rd harmonics at 20MHz
- -3dB bandwidth of 270MHz
- 0.05% settling in 15ns
- 3000V/ $\mu$ s slew rate
- 1mV input offset voltage, 10 $\mu$ V/ $^{\circ}$ C drift
- $\pm$ 10V, 100mA max output
- Direct replacement for CLC232

### Applications

- Flash A/D drivers
- DAC current-to-voltage conversion
- Wide dynamic range IF amps
- VCO drivers
- DDS postamps
- Radar/communication receivers
- Precision line drivers



Bottom View



Pins 2 and 8 are used to adjust the supply current or to adjust the offset voltage (see text). These pins are normally left unconnected.

### General Description

The KH232 is a wideband low distortion operational amplifier designed specifically for high speed, low gain applications requiring wide dynamic range. Utilizing a current feedback architecture, the KH232 offers high speed performance while maintaining DC precision.

The KH232 offers precise gains from  $\pm$ 1 to  $\pm$ 5 with a true 0.1% linearity and provides stable, oscillation-free operation across the entire gain range without external compensation. The KH232, a pin compatible enhanced version of the KH231, reduces 2nd and 3rd harmonic distortion to an extremely low -69dBc at 20MHz (2V<sub>pp</sub>, R<sub>L</sub> = 100 $\Omega$ ). Additional features provided by the KH232 include a small signal bandwidth of 270MHz, a large signal bandwidth of 95MHz and a 3000V/ $\mu$ s slew rate. The input offset voltage is typically 1mV with an input offset drift of 10 $\mu$ V/ $^{\circ}$ C.

The KH232 combines these high performance features with its 0.05% settling time of 15ns and its 100mA drive capability to provide high speed, high resolution A/D and D/A converter systems with an attractive solution for driving and buffering. Wide dynamic range systems such as radar and communication receivers requiring low harmonic distortion and low noise will find the KH232 to be an excellent choice. As a line driver, the KH232 set at a gain of 2 cancels matched line losses.

The KH232 is constructed using thin film resistor/bipolar transistor technology, and is available in the following versions:

KH232AI	-25 $^{\circ}$ C to +85 $^{\circ}$ C	12-pin TO-8 can
KH232AK	-55 $^{\circ}$ C to +125 $^{\circ}$ C	12-pin TO-8 can, features burn-in & hermetic testing
KH232AM	-55 $^{\circ}$ C to +125 $^{\circ}$ C	12-pin TO-8 can, environmentally screened and electrically tested to MIL-STD-883
KH232HXC	-55 $^{\circ}$ C to +125 $^{\circ}$ C	SMD#: 5962-9166501HXC
KH232HXA	-55 $^{\circ}$ C to +125 $^{\circ}$ C	SMD#: 5962-9166501HXA

### Typical Performance

Parameter	Gain Setting						Units
	1	2	5	-1	-2	-5	
-3dB bandwidth	430	270	135	220	175	110	MHz
rise time (2V)	1.8	2.0	2.5	2.0	2.2	2.9	ns
slew rate	2.5	3.0	3.0	3.0	3.0	3.0	V/ns
settling time (to 0.1%)	12	12	12	12	12	15	ns

## KH232 Electrical Characteristics ( $T_A = +25^\circ\text{C}$ , $A_V = +2\text{V}$ , $V_{CC} = \pm 15\text{V}$ , $R_L = 100\Omega$ , $R_f = 250\Omega$ ; unless specified)

PARAMETERS	CONDITIONS	TYP	MIN & MAX RATINGS			UNITS	SYM
			-25°C	+25°C	+85°C		
Ambient Temperature	KH232AI	+25°C	-25°C	+25°C	+85°C		
Ambient Temperature	KH232AK/AM/HXC/HXA	+25°C	-55°C	+25°C	+125°C		
<b>FREQUENCY DOMAIN RESPONSE</b>							
† -3dB bandwidth (note 2)	$V_o \leq 0.63V_{pp}$	270	>200	>200	>200	MHz	SSBW
	$V_o \leq 2V_{pp}$	165	>145	>145	>120	MHz	SSBW
large-signal bandwidth	$V_o \leq 10V_{pp}$	95	>80	>80	>60	MHz	FPBW
gain flatness (note 2)	$V_o \leq 0.63V_{pp}$						
† peaking	0.1 to 50MHz	0.1	<0.6	<0.3	<0.6	dB	GFPL
† peaking	>50MHz	0.1	<1.5	<0.3	<0.8	dB	GFPH
† rolloff	at 100MHz	0.4	<0.6	<0.6	<1.0	dB	GFR
group delay	to 100MHz	3.5 ± 0.5	–	–	–	ns	GD
linear phase deviation	to 100MHz	0.5	<2.0	<2.0	<2.0	°	LPD
reverse isolation							
non-inverting		53	>43	>43	>43	dB	RINI
inverting		36	>26	>26	>26	dB	RIIN
<b>TIME DOMAIN RESPONSE</b>							
rise and fall time	2V step	2.0	<2.4	<2.3	<2.7	ns	TRS
	10V step	5.0	<7.0	<6.5	<6.5	ns	TRL
settling time to 0.05%	5V step	15	–	–	–	ns	TS
to 0.1%	2.5V step	12	<22	<17	<22	ns	TSP
overshoot	5V step	5	<15	<10	<15	%	OS
slew rate (overdriven input)		3.0	>2.5	>2.5	>1.8	V/ns	SR
overload recovery	<1% error						
<50ns pulse, 200% overdrive		120	–	–	–	ns	OR
<b>NOISE AND DISTORTION RESPONSE</b>							
† 2nd harmonic distortion	2V <sub>pp</sub> , 20MHz	-69	<-64	<-64	<-56	dBc	HD2
† 3rd harmonic distortion	2V <sub>pp</sub> , 20MHz	-69	<-64	<-64	<-64	dBc	HD3
equivalent input noise							
voltage	>100kHz	2.8	<3.2	<3.2	<3.5	nV/√Hz	VN
inverting current	>100kHz	20	<23	<23	<25	pA/√Hz	ICN
non-inverting current	>100kHz	2.3	<2.6	<2.6	<2.9	pA/√Hz	NCN
noise floor	>100kHz	-155	<-154	<-154	<-153	dBm(1Hz)	SNF
integrated noise	1kHz to 200MHz	57	<64	<64	<72	μVrms	INV
integrated noise	5MHz to 200MHz	57	<64	<64	<72	μVrms	INV
<b>STATIC, DC PERFORMANCE</b>							
* input offset voltage		1	<4.0	<2.0	<4.5	mV	VIO
average temperature coefficient		10	<25	<25	<25	μV/°C	DVIO
* input bias current	non-inverting	5.0	<29	<21	<31	μA	IBN
average temperature coefficient		50	<125	<125	<125	nA/°C	DIBN
* input bias current	inverting	10	<31	<15	<35	μA	IBI
average temperature coefficient		125	<200	<200	<200	nA/°C	DIBI
* power supply rejection ratio		50	>45	>45	>45	dB	PSRR
common mode rejection ratio		46	>40	>40	>40	dB	CMRR
* supply current	no load	25	<27	<27	<29	mA	ICC
<b>MISCELLANEOUS PERFORMANCE</b>							
non-inverting input resistance	DC	400	>100	>200	>400	kΩ	RIN
non-inverting input capacitance		1.3	<2.5	<2.5	<2.5	pF	CIN
output impedance	@ 100MHz	5, 37	–	–	–	Ω, nH	RO
output voltage range	no load	±12	>±11	>±11	>±11	V	VO

Min/max ratings are based on product characterization and simulation. Individual parameters are tested as noted. Outgoing quality levels are determined from tested parameters.

### Absolute Maximum Ratings

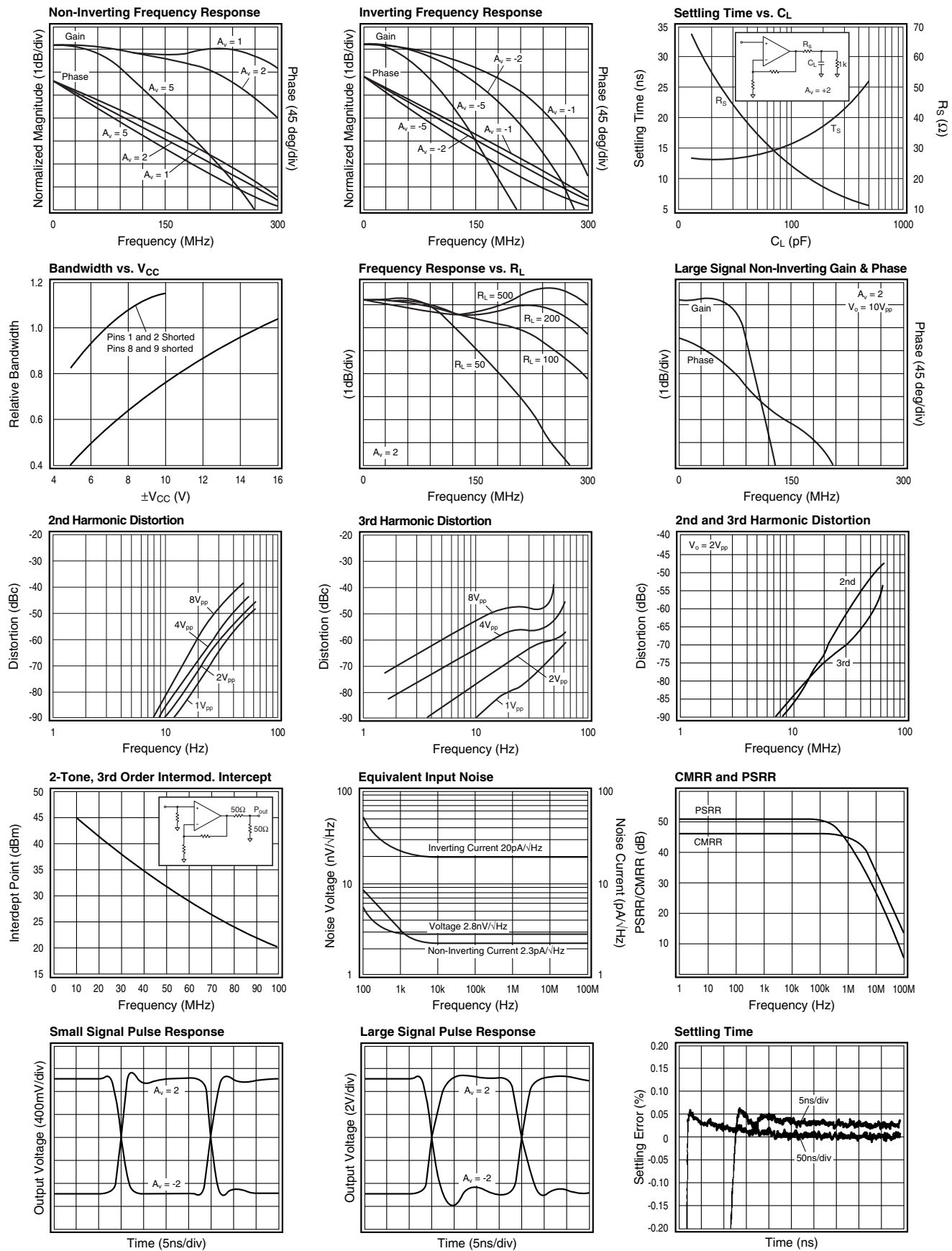
$V_{CC}$	±20V
$I_o$	±100mA
common mode input voltage, $V_o$	$ V_{CC}  > 15\text{V} \pm (30 -  V_{CC} )\text{V}$ $ V_{CC}  \leq 15\text{V} \pm  V_{CC} \text{V}$
differential input voltage	±3V
thermal resistance	(see thermal model)
junction temperature	+175°C
operating temperature	AI: -25°C to +85°C AK/AM/HXC/HXA: -55°C to +125°C
storage temperature	-65°C to +150°C
lead temperature (soldering 10s)	+300°C

### Recommended Operating Conditions

$V_{CC}$	±5V to ±15V
$I_o$	±75mA
common mode input voltage	±( V <sub>CC</sub>   - 5)V
gain range	±1 to ±5

- note 1:**
- \* AI/AK/AM/HXC/HXA 100% tested at +25°C
  - † AK/AM/HXC/HXA 100% tested at +25°C and sample tested at -55°C and +125°C
  - † AI sample tested at +25°C
- note 2:** The output amplitude used in testing is 0.63V<sub>pp</sub>. Performance is guaranteed for conditions listed.

# KH232 Typical Performance Characteristics ( $T_A = +25^\circ\text{C}$ , $A_v = +2$ , $V_{CC} = \pm 15\text{V}$ , $R_L = 100\Omega$ , $R_f = 250\Omega$ ; unless specified)



**Operation**

The KH232 is based on the current feedback op amp topology, a design that uses current feedback instead of the usual voltage feedback.

The use of the KH232 is basically the same as that of the conventional op amp (see Figures 1 and 2). Since the device is designed specifically for low gain applications, the best performance is obtained when the circuit is used at gains between ±1 and ±5. Additionally, performance is optimum when a 250Ω feedback resistor is used.

**Layout Considerations**

To assure optimum performance the user should follow good layout practices which minimize the unwanted coupling of signals between nodes. During initial bread-boarding of the circuit use direct point to point wiring, keeping the lead lengths to less than 0.25". The use of solid, unbroken ground plane is helpful. Avoid wire-wrap type pc boards and methods. Sockets with small, short pin receptacles may be used with minimal performance degradation although their use is not recommended.

During pc board layout keep all traces short and direct. The resistive body of R<sub>g</sub> should be as close as possible to pin 5 to minimize capacitance at that point. For the same reason, remove ground plane from the vicinity of pins 5 and 6. In other areas, use as much ground plane as possible on one side of the board. It is especially important to provide a ground return path for current from the load resistor to the power supply bypass capacitors. Ceramic capacitors of 0.01 to 0.1μf (with short leads) should be less than 0.15 inches from pins 1 and 9. Larger tantalum capacitors should be placed within one inch of these pins. V<sub>CC</sub> connections to pins 10 and 12 can be made directly from pins 9 and 1, but better supply rejection and settling time are obtained if they are separately bypassed as in figures 1 and 2. To prevent signal distortion caused by reflections from impedance mismatches, use terminated microstrip or coaxial cable when the signal must traverse more than a few inches.

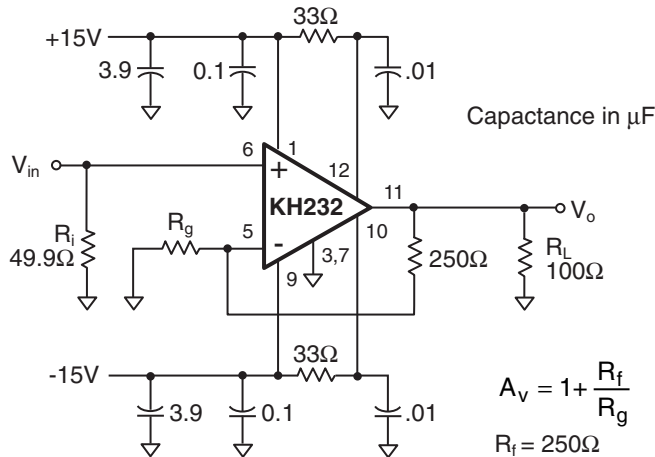
Since the pc board forms such an important part of the circuit, much time can be saved if prototype boards of any high frequency sections are built and tested early in the design phase. Evaluation boards designed for either inverting or non-inverting gains are available.

**Offset Voltage Adjustment**

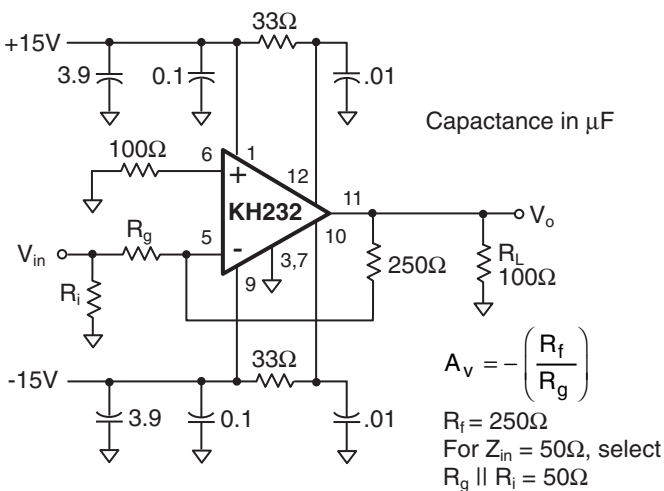
If trimming of the input offset voltage (V<sub>os</sub> = V<sub>ni</sub> - V<sub>in</sub>) is desired, a resistor value of 10kΩ to 1MΩ placed between pins 8 and 9 will cause V<sub>os</sub> to become more negative by 8mV to 0.2mV respectively. Similarly, a resistor placed between pins 1 and 2 will cause V<sub>os</sub> to become more positive.

**Thermal Considerations**

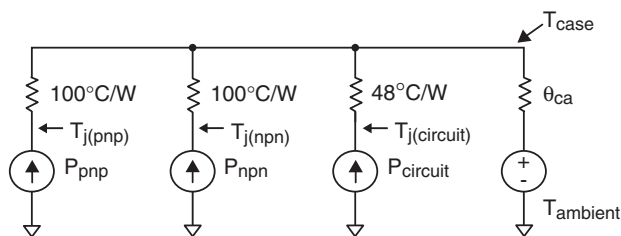
At high ambient temperatures or large internal power dissipations, heat sinking is required to maintain acceptable junction temperatures. Use the thermal model on the previous page to determine junction temperatures. Many styles of heat sinks are available for TO-8 packages; the Thermalloy 2240 and 2268 are good examples. Some heat sinks are the radial fin type which cover the pc board and may interfere with external components. An excellent solution to this problem is to use surface mounted resistors and capacitors. They have a very low profile and actually improve high frequency performance. For use of these heat sinks with conventional components, a 0.1" high spacer can be inserted under the TO-8 package to allow sufficient clearance.



**Figure 1: Recommended non-inverting gain circuit**



**Figure 2: Recommended inverting gain circuit**



$$P_{(\text{circuit})} = (I_{CC})(+V_{CC} - V_{CC}) \text{ where } I_{CC} = 14\text{mA at } \pm 15\text{V}$$

$$P_{(\text{xxx})} = [(\pm V_{CC}) - V_{\text{out}} - (I_{\text{col}})(R_{\text{col}} + 4)](I_{\text{col}})(\% \text{Duty})$$

For positive  $V_o$  and  $V_{CC}$ , this is the power in the npn device. For negative  $V_o$  and  $V_{CC}$ , this is the power in the pnp device.

$I_{\text{col}} = V_o/R_L$  or 12mA, whichever is greater. (Include feedback R in  $R_L$ .)

$R_{\text{col}}$  is a resistor (33 $\Omega$  recommended) between the xxx collector and  $\pm V_{CC}$ .

The limiting factor for output current and voltage is junction temperature. Of secondary importance is  $I_{(\text{out})}$ , which should not exceed 150mA.

$$T_{j(\text{pnp})} = P_{(\text{pnp})}(100 + \theta_{\text{ca}}) + (P_{(\text{cir})} + P_{(\text{npn})})(\theta_{\text{ca}}) + T_a,$$

similar for  $T_{j(\text{npn})}$ .

$$T_{j(\text{cir})} = P_{(\text{cir})}(48 + \theta_{\text{ca}}) + (P_{(\text{pnp})} + P_{(\text{npn})})(\theta_{\text{ca}}) + T_a.$$

$\theta_{\text{ca}} = 65^\circ\text{C/W}$  for the KH232 without heat sink in still air.  
 $35^\circ\text{C/W}$  for the KH232 with a Thermalloy 2268A heat sink in still air.  
 $15^\circ\text{C/W}$  for the KH232 with a Thermalloy 2268A heat sink at 300 ft/min air.  
 (Thermalloy 2240A works equally as well.)

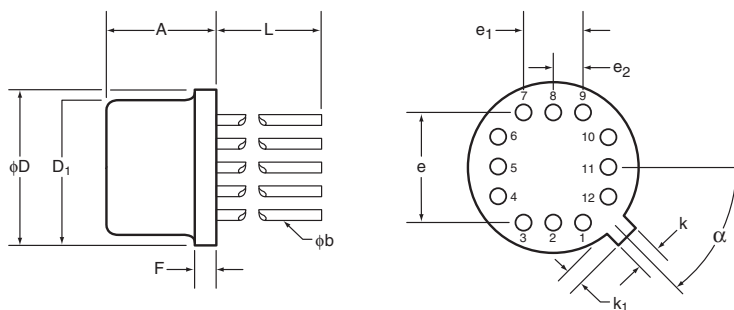
For example, with the KH232 operating at  $\pm 15\text{V}$  while driving a 100 $\Omega$  load at 15V<sub>pp</sub> output (50% duty cycle pulse waveform, DC = 0),  $P_{(\text{npn})} = P_{(\text{pnp})} = 190\text{mW}$  ( $R_{\text{col}} = 33$ ) and  $P_{(\text{cir})} = 0.42\text{W}$ . Then with the Thermalloy 2268 heat sink and air flow of 300 ft/min the output transistors'  $T_j$  is 31 $^\circ\text{C}$  above ambient and worst case  $T_j$  in the rest of the circuit is 32 $^\circ\text{C}$  above ambient. In still air, however, the rise in  $T_j$  is 47 $^\circ\text{C}$  and 48 $^\circ\text{C}$ , respectively. With no heat sink, the rise in  $T_j$  is 71 $^\circ\text{C}$  and 72 $^\circ\text{C}$ , respectively! Under most conditions, **HEAT SINKING IS REQUIRED.**

Other methods of heat sinking may be used, but for best results, make contact with the base of the KH232 package, use a large thermal capacity heat sink and use forced air convection.

#### Low $V_{CC}$ Operation: Supply Current Adjustment

The KH232 is designed to operate on supplies as low as  $\pm 5\text{V}$ . In order to improve full bandwidth at reduced supply voltages, the supply current ( $I_{CC}$ ) must be increased. The plot of Bandwidth vs.  $V_{CC}$ , shows the effect of shorting pins 1 and 2 and pins 8 and 9; this will increase both bandwidth and supply current. Care should be taken to not exceed the maximum junction temperatures; for this reason this technique should not be used with supplies exceeding  $\pm 10\text{V}$ . For intermediate values of  $V_{CC}$ , external resistors between pins 1 and 2 and pins 8 and 9 can be used.

### KH232 Package Dimensions



TO-8				
SYMBOL	INCHES		MILIMETERS	
	Minimum	Maximum	Minimum	Maximum
A	0.142	0.181	3.61	4.60
$\phi b$	0.016	0.019	0.41	0.48
$\phi D$	0.595	0.605	15.11	15.37
$\phi D_1$	0.543	0.555	13.79	14.10
e	0.400 BSC		10.16 BSC	
e <sub>1</sub>	0.200 BSC		5.08 BSC	
e <sub>2</sub>	0.100 BSC		2.54 BSC	
F	0.016	0.030	0.41	0.76
k	0.026	0.036	0.66	0.91
k <sub>1</sub>	0.026	0.036	0.66	0.91
L	0.310	0.340	7.87	8.64
$\alpha$	45° BSC		45° BSC	

**NOTES:**  
 Seal: cap weld  
 Lead finish: gold per MIL-M-38510  
 Package composition:  
 Package: metal  
 Lid: Type A per MIL-M-38510

**For Further Assistance:**

**Exar Corporation Headquarters and Sales Offices**  
 48720 Kato Road Tel.: +1 (510) 668-7000  
 Fremont, CA 94538 - USA Fax: +1 (510) 668-7001  
 www.exar.com



A New Direction in Mixed-Signal

**NOTICE**

EXAR Corporation reserves the right to make changes to the products contained in this publication in order to improve design, performance or reliability. EXAR Corporation assumes no responsibility for the use of any circuits described herein, conveys no license under any patent or other right, and makes no representation that the circuits are free of patent infringement. Charts and schedules contained here in are only for illustration purposes and may vary depending upon a user's specific application. While the information in this publication has been carefully checked; no responsibility, however, is assumed for inaccuracies.

EXAR Corporation does not recommend the use of any of its products in life support applications where the failure or malfunction of the product can reasonably be expected to cause failure of the life support system or to significantly affect its safety or effectiveness. Products are not authorized for use in such applications unless EXAR Corporation receives, in writing, assurances to its satisfaction that: (a) the risk of injury or damage has been minimized; (b) the user assumes all such risks; (c) potential liability of EXAR Corporation is adequately protected under the circumstances.

Reproduction, in part or whole, without the prior written consent of EXAR Corporation is prohibited.